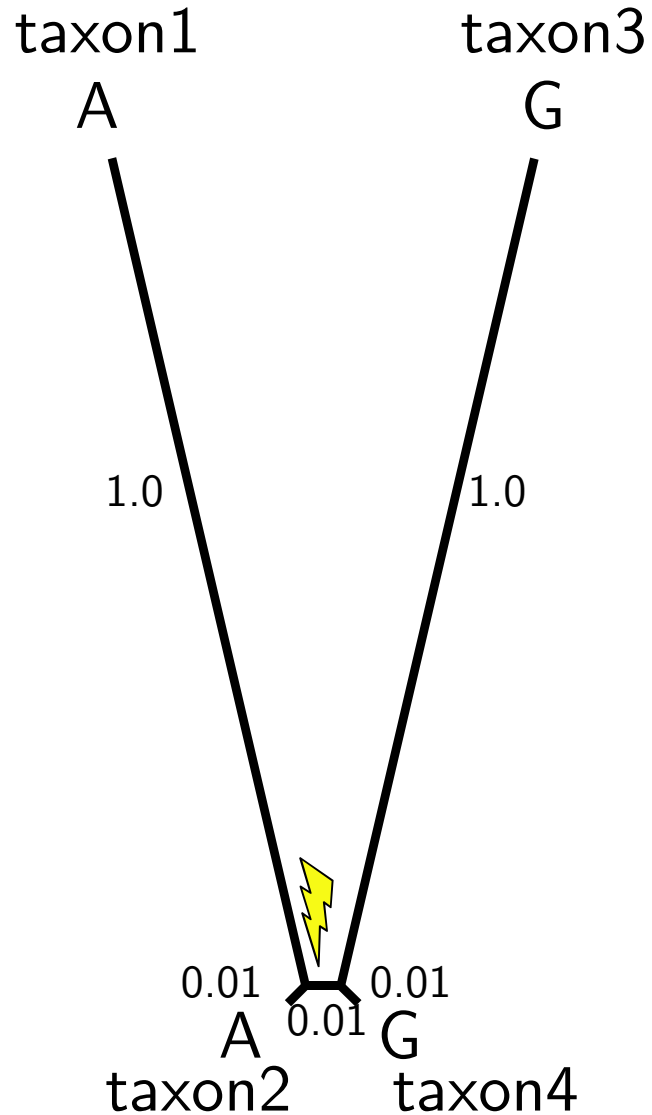


Thanks to Paul Lewis and Joe Felsenstein for the use of slides

Review

- Hennigian logic reconstructs the tree if we know **polarity** of characters and there is **no homoplasy**
- UPGMA infers a tree from a distance matrix:
 - groups based on **similarity**
 - fails to give the correct tree if rates of character evolution vary much
- Modern distance-based approaches:
 - find trees and branch lengths: patristic distances \approx distances from character data.
 - do **not** use all of the information in the data.
- Parsimony:
 - prefer the tree that **requires** the fewest character state changes. Minimize the number of times you invoke homoplasy to explain the data.
 - can work well if homoplasy is not rare
 - fails if homoplasy very common **or is concentrated on certain parts of the tree**

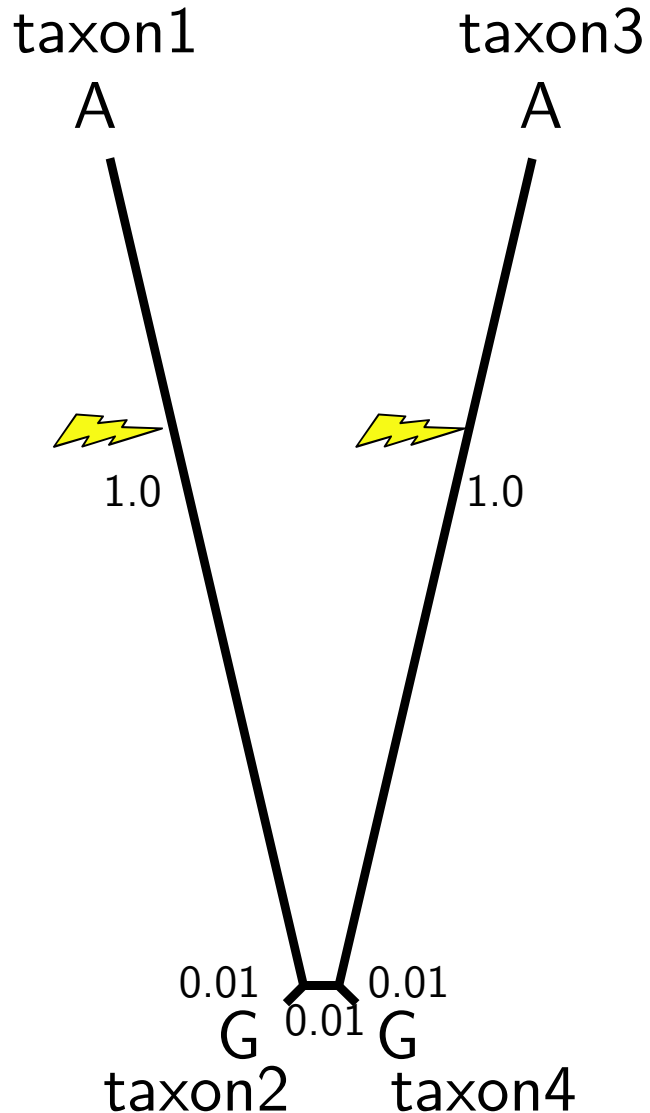
Long branch attraction



Felsenstein, J. 1978. Cases in which parsimony or compatibility methods will be positively misleading. *Systematic Zoology* 27: 401-410.

The probability of a parsimony informative site due to inheritance is very low, (roughly 0.0003).

Long branch attraction



Felsenstein, J. 1978. Cases in which parsimony or compatibility methods will be positively misleading. *Systematic Zoology* 27: 401-410.

The probability of a parsimony informative site due to inheritance is very low, (roughly 0.0003).

The probability of a misleading parsimony informative site due to parallelism is much higher (roughly 0.008).

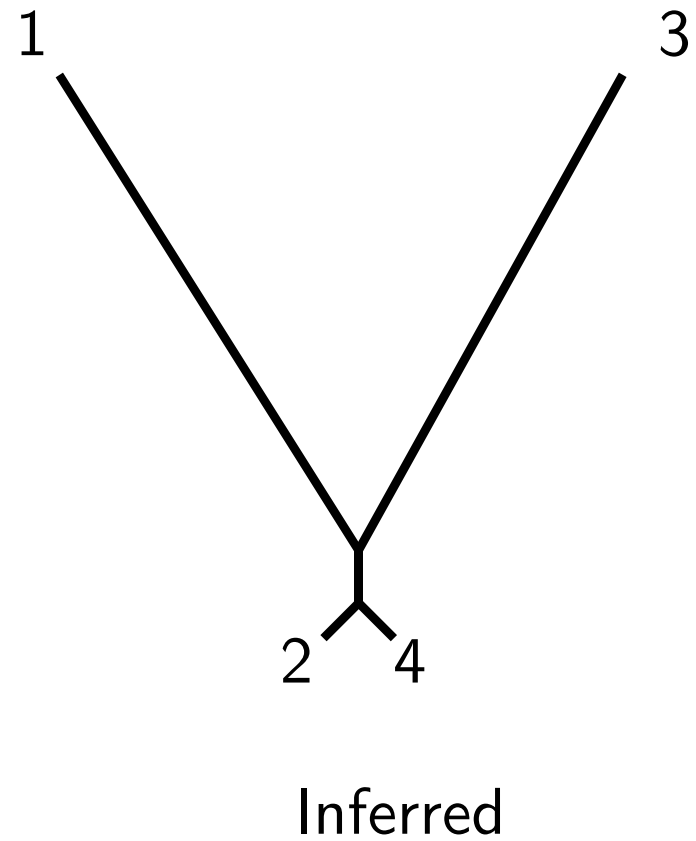
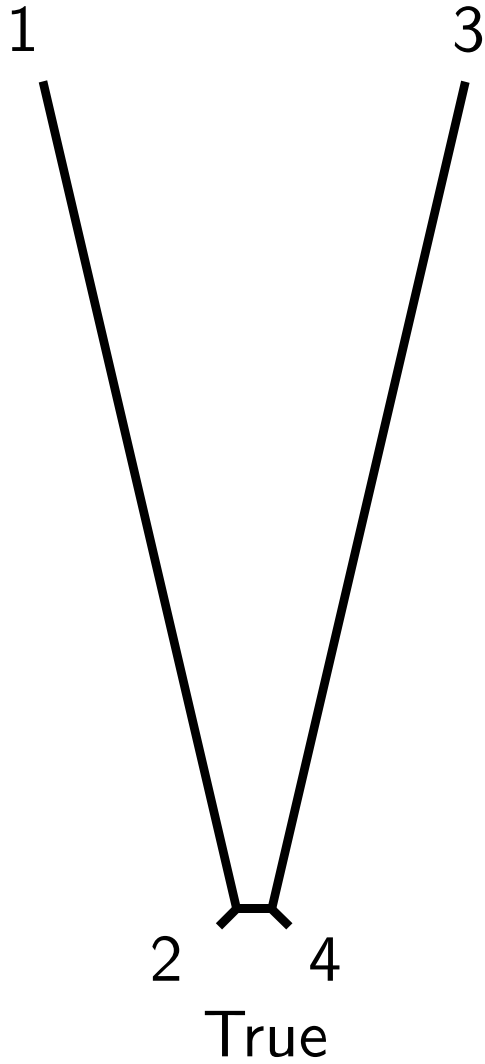
Long branch attraction data

Under such a tree misleading characters are more common than characters that favor the true tree.

| | Rare | | | | | Common | | | |
|--------|------|---|---|---|--|--------|---|---|---|
| taxon1 | A | A | C | C | | A | A | C | C |
| taxon2 | A | A | C | C | | G | C | T | G |
| taxon3 | G | C | T | G | | A | A | C | C |
| taxon4 | G | C | T | G | | G | C | T | G |

Long branch attraction

Parsimony is almost guaranteed to get this tree wrong.



Likelihood

X is the data.

T is the tree.

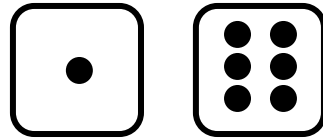
ν is a vector of branch lengths.

$\Pr(X|T, \nu)$ is the *likelihood*; this is sometimes denoted $L(T, \nu)$.

Maximum likelihood: find the T and ν that gives the highest likelihood.

Combining probabilities

- Multiply probabilities if the component events must happen simultaneously (i.e. wherever you would naturally use the word AND when describing the problem)

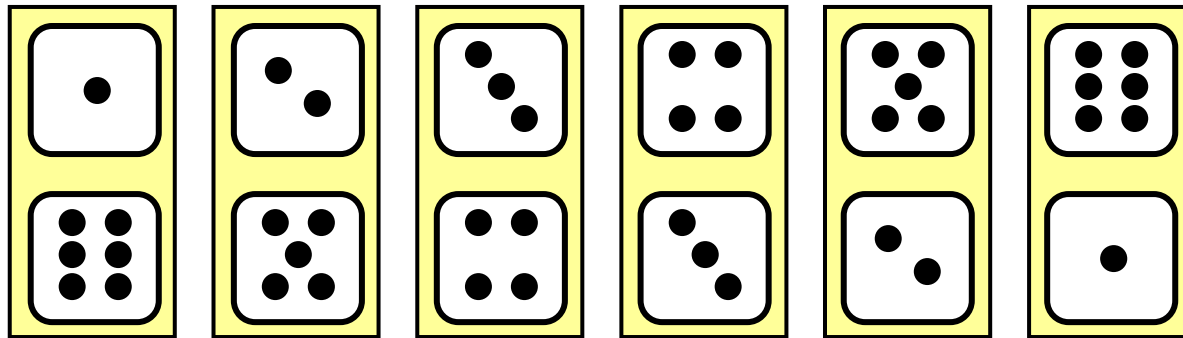


$$(1/6) \times (1/6) = 1/36$$

What is the probability of rolling two dice and having the first show 1 dot AND the second show 6 dots?

Combining probabilities

- Add probabilities if the component events are mutually exclusive (i.e. wherever you would naturally use the word OR)



$$(1/36) + (1/36) + (1/36) + (1/36) + (1/36) + (1/36) = 1/6$$

What is the probability of rolling 7 using two dice? This is the same as asking "What is the probability of rolling (1 and 6) OR (2 and 5) OR (3 and 4) OR (4 and 3) OR (5 and 2) OR (6 and 1)?"

Likelihood of a single sequence

First 32 nucleotides of the $\psi\eta$ -globin gene of gorilla:

GAAGTCCTTGAGAAATAAACTGCACACACTGG

$$\begin{aligned} L &= \pi_G \pi_A \pi_A \pi_G \pi_T \pi_C \pi_C \pi_T \pi_T \pi_G \pi_A \pi_G \pi_A \pi_A \pi_A \pi_T \pi_A \pi_A \pi_A \pi_C \pi_T \pi_G \pi_C \pi_A \pi_C \pi_A \pi_C \pi_A \pi_C \pi_T \pi_G \pi_G \\ &= \pi_A^{12} \pi_C^7 \pi_G^7 \pi_T^6 \end{aligned}$$

$$\ln L = 12 \ln(\pi_A) + 7 \ln(\pi_C) + 7 \ln(\pi_G) + 6 \ln(\pi_T)$$

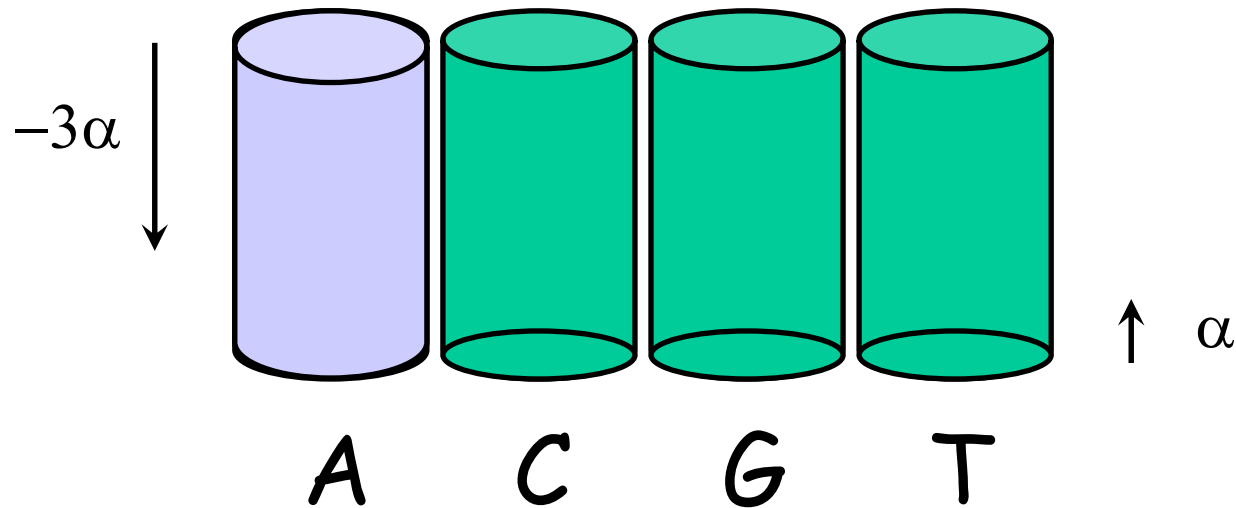
We can already see by eye-balling this that the F81 model (which allows unequal base frequencies) will fit better than the JC69 model (which assumes equal base frequencies) because there are about twice as many As as there are Cs, Gs and Ts.

Likelihoods on the simplest possible tree

GA \rightarrow **GG**

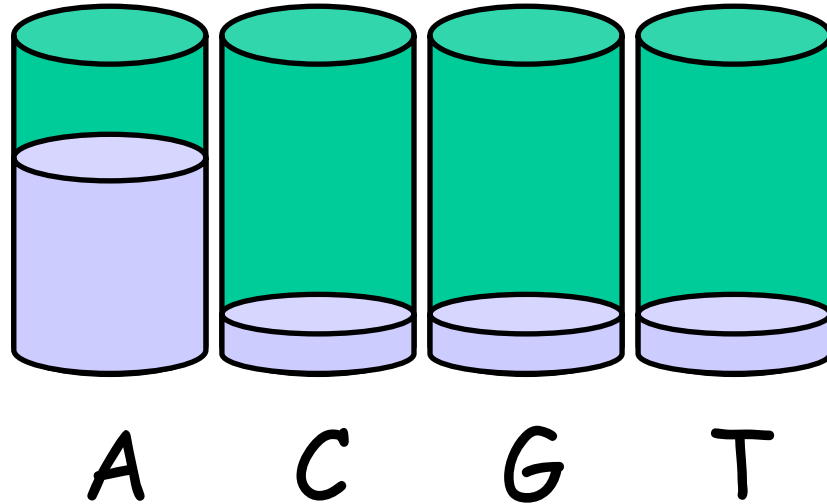
$$\begin{aligned} L &= L_1 L_2 \\ &= \Pr(G) \Pr(G \rightarrow G) \Pr(A) \Pr(A \rightarrow G) \\ &= \Pr(G) \Pr(G \rightarrow G|\nu) \Pr(A) \Pr(A \rightarrow G|\nu) \end{aligned}$$

Water analogy (time 0)



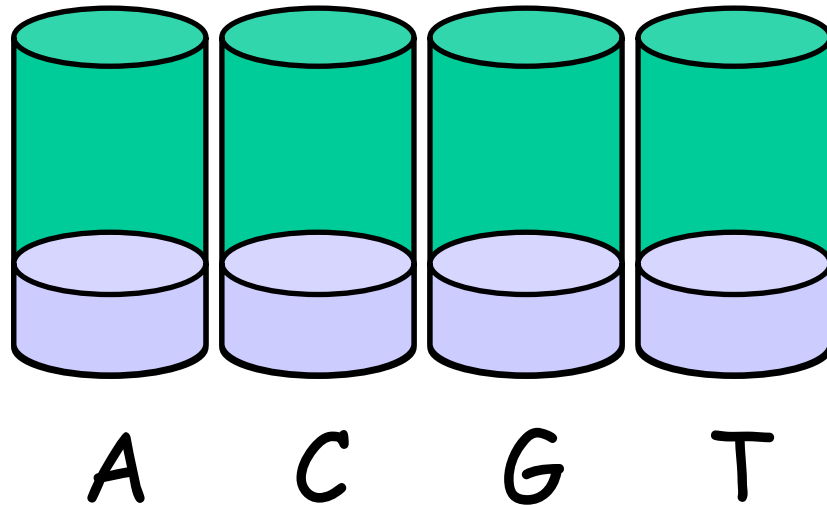
- Start with container A completely full and others empty
- Imagine that all containers are connected by tubes that allow same rate of flow between any two
- Initially, A will be losing water at 3 times the rate that C (or G or T) gains water

Water analogy (after some time)



A's level is not dropping as fast now because it is now also *receiving* water from C, G and T

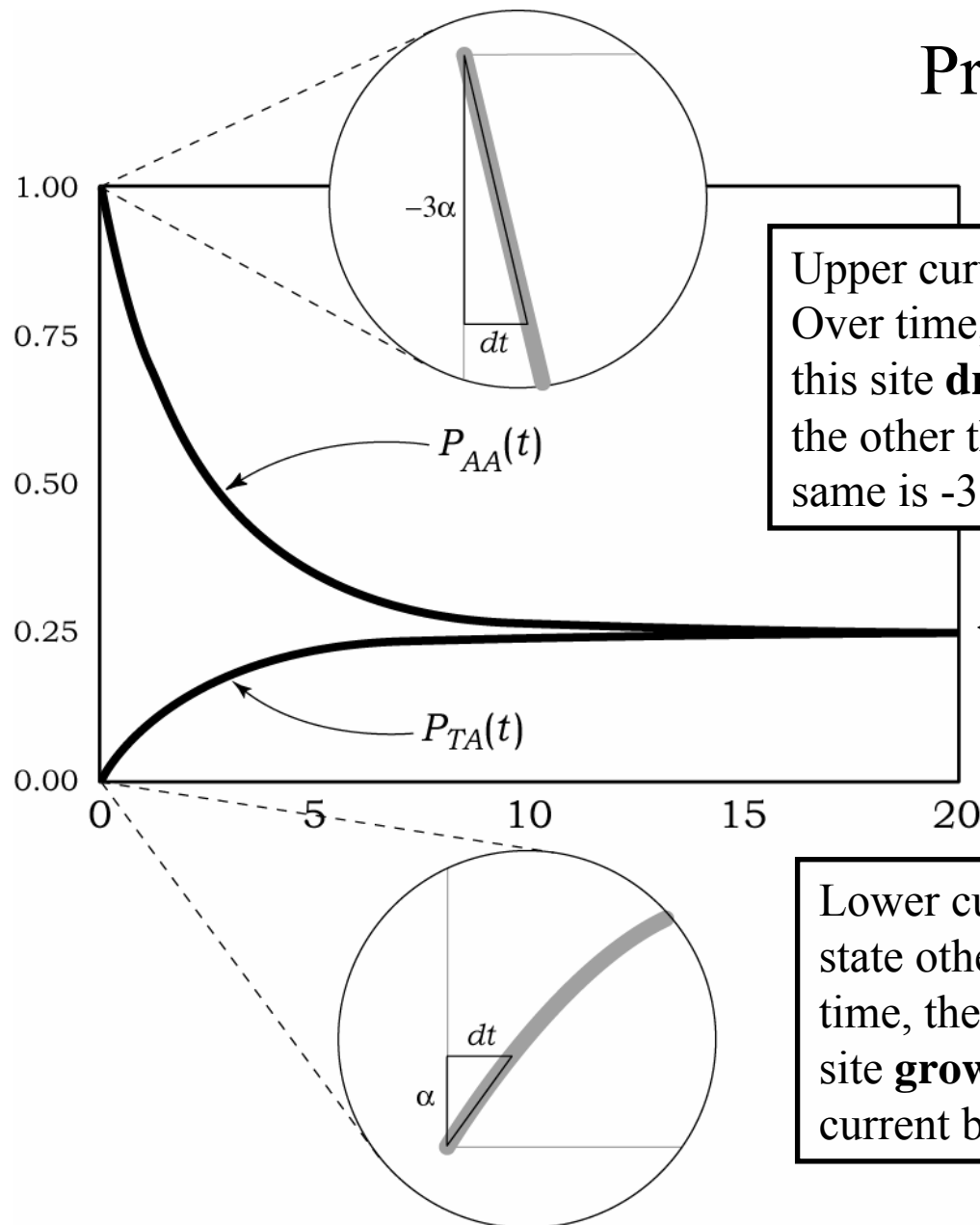
Water analogy (after a very long time)



Eventually, all containers are one fourth full and there is zero *net* volume change – **stationarity** (equilibrium) has been achieved

(Thanks to Kent Holsinger for this analogy)

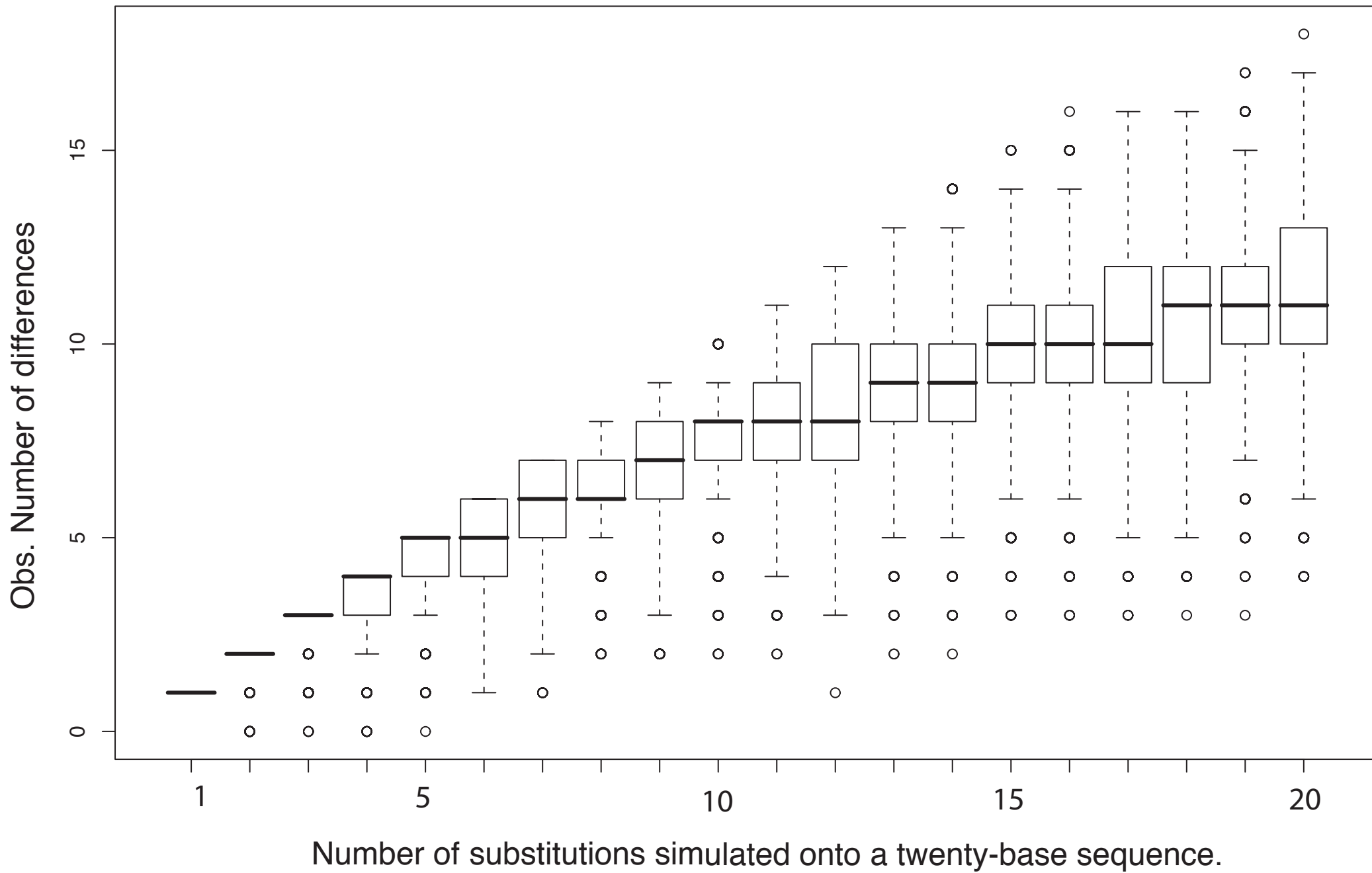
Probability of “A present” as a function of time



Upper curve assumes we started with A at time 0. Over time, the probability of still seeing an A at this site **drops** because rate of changing to one of the other three bases is 3α (so rate of staying the same is -3α).

The equilibrium relative frequency of A is 0.25

Lower curve assumes we started with some state other than A (T is used here). Over time, the probability of seeing an A at this site **grows** because the rate at which the current base will change into an A is α .



Jukes-Cantor model

$$\Pr(G \rightarrow G|\nu) = \frac{1}{4} + \frac{3}{4} e^{-\frac{4\nu}{3}}$$

$$\Pr(A \rightarrow G|\nu) = \frac{1}{4} - \frac{1}{4} e^{-\frac{4\nu}{3}}$$

Likelihoods on the simplest possible tree

GA \rightarrow **GG**

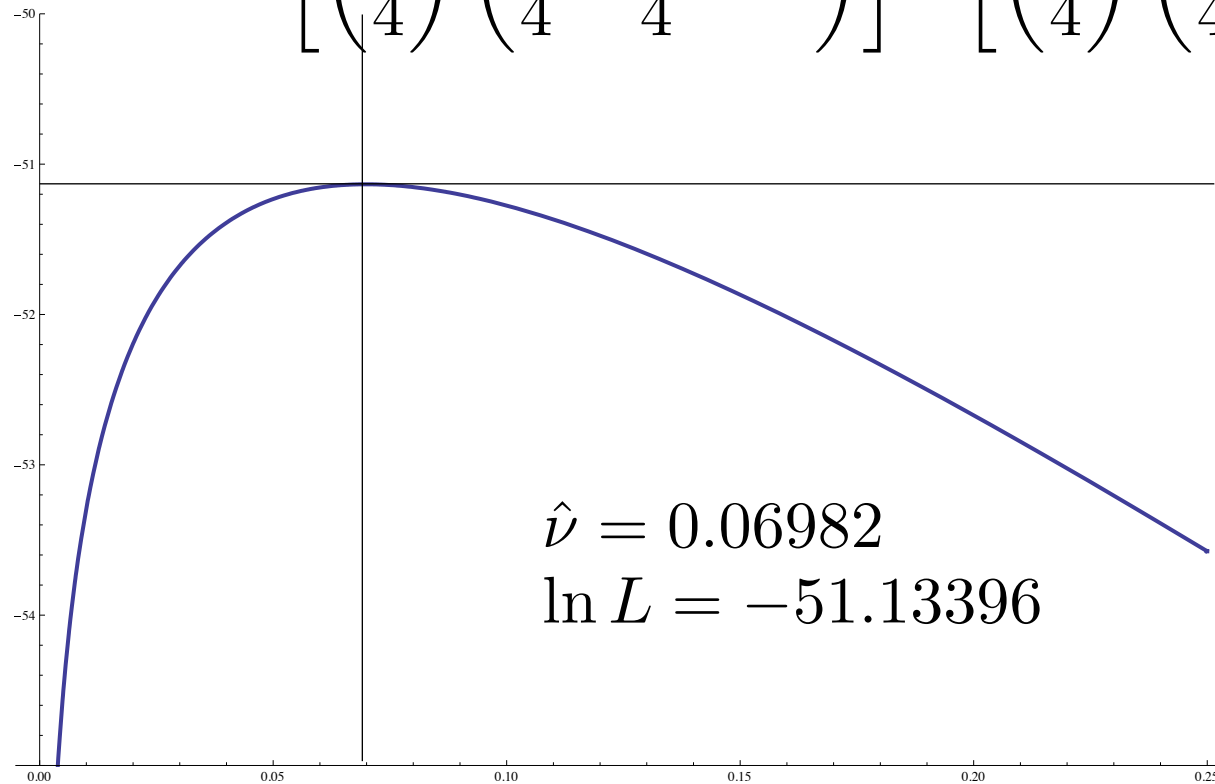
$$\begin{aligned} L &= L_1 L_2 \\ &= \Pr(G) \Pr(G \rightarrow G) \Pr(A) \Pr(A \rightarrow G) \\ &= \Pr(G) \Pr(G \rightarrow G|\nu) \Pr(A) \Pr(A \rightarrow G|\nu) \\ &= \left(\frac{1}{4}\right) \left(\frac{1}{4} + \frac{3}{4} e^{-\frac{4\nu}{3}}\right) \left(\frac{1}{4}\right) \left(\frac{1}{4} - \frac{1}{4} e^{-\frac{4\nu}{3}}\right) \end{aligned}$$

The first 30 nucleotides of the $\psi\eta$ -globin gene

gorilla GAAGTCCTTGAGAAATAAACTGCACACTGG

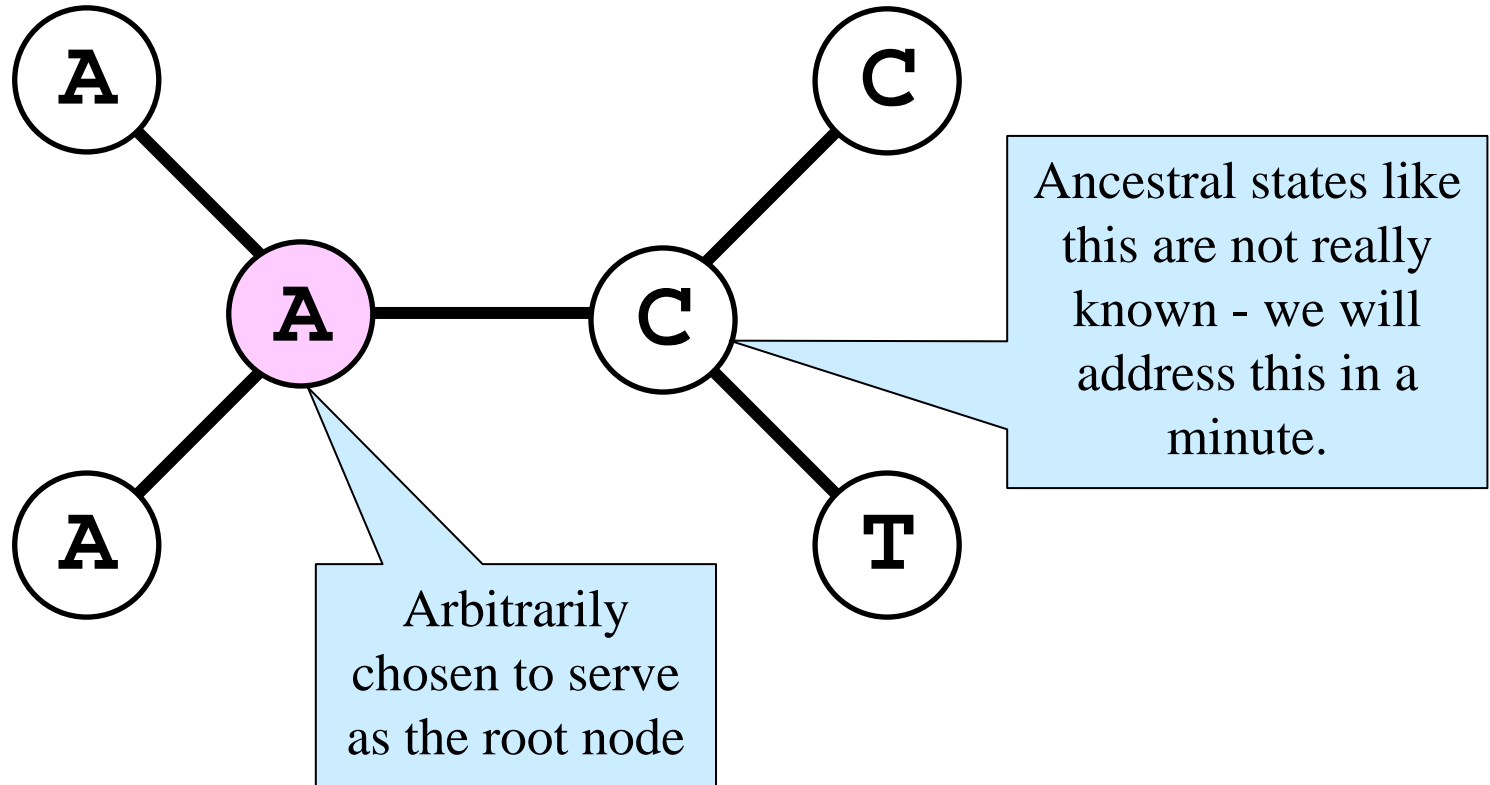
orangutan GGACTCCTTGAGAAATAAACTGCACACTGG

$$L = \left[\begin{pmatrix} 1 \\ \frac{1}{4} \end{pmatrix} \begin{pmatrix} 1 \\ \frac{1}{4} + \frac{3}{4} e^{-\frac{4\nu}{3}} \end{pmatrix} \right]^{28} \left[\begin{pmatrix} 1 \\ \frac{1}{4} \end{pmatrix} \begin{pmatrix} 1 \\ \frac{1}{4} - \frac{1}{4} e^{-\frac{4\nu}{3}} \end{pmatrix} \right]^2$$

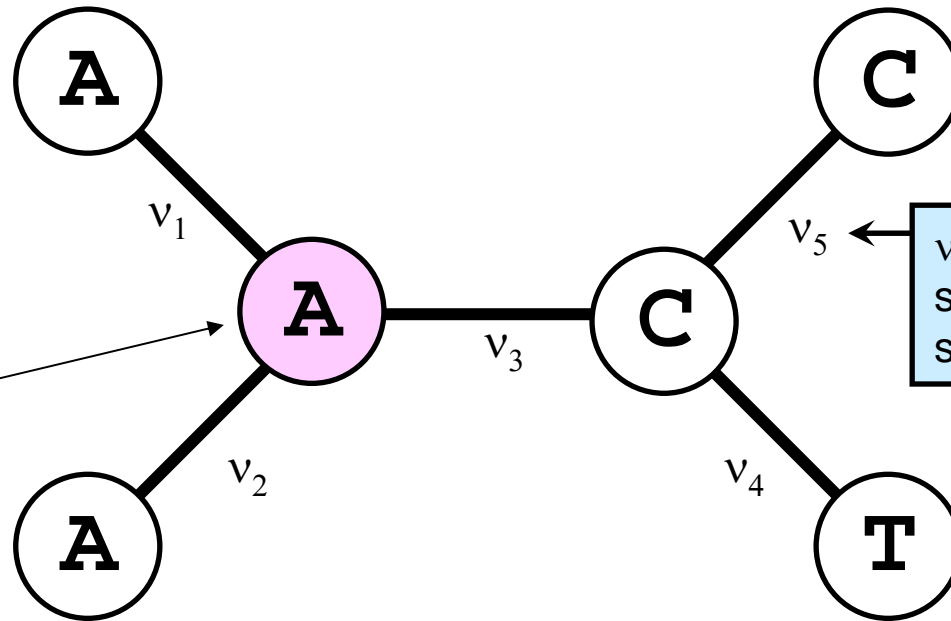


Likelihood of a tree

(data for only one site shown)



Likelihood for site k



$$L_k = \frac{1}{4} \left[\frac{1}{4} + \frac{3}{4} e^{-4v_1/3} \right] \left[\frac{1}{4} + \frac{3}{4} e^{-4v_2/3} \right] \left[\frac{1}{4} - \frac{1}{4} e^{-4v_3/3} \right] \left[\frac{1}{4} - \frac{1}{4} e^{-4v_4/3} \right] \left[\frac{1}{4} + \frac{3}{4} e^{-4v_5/3} \right]$$

$P_{AA}(v_1)$

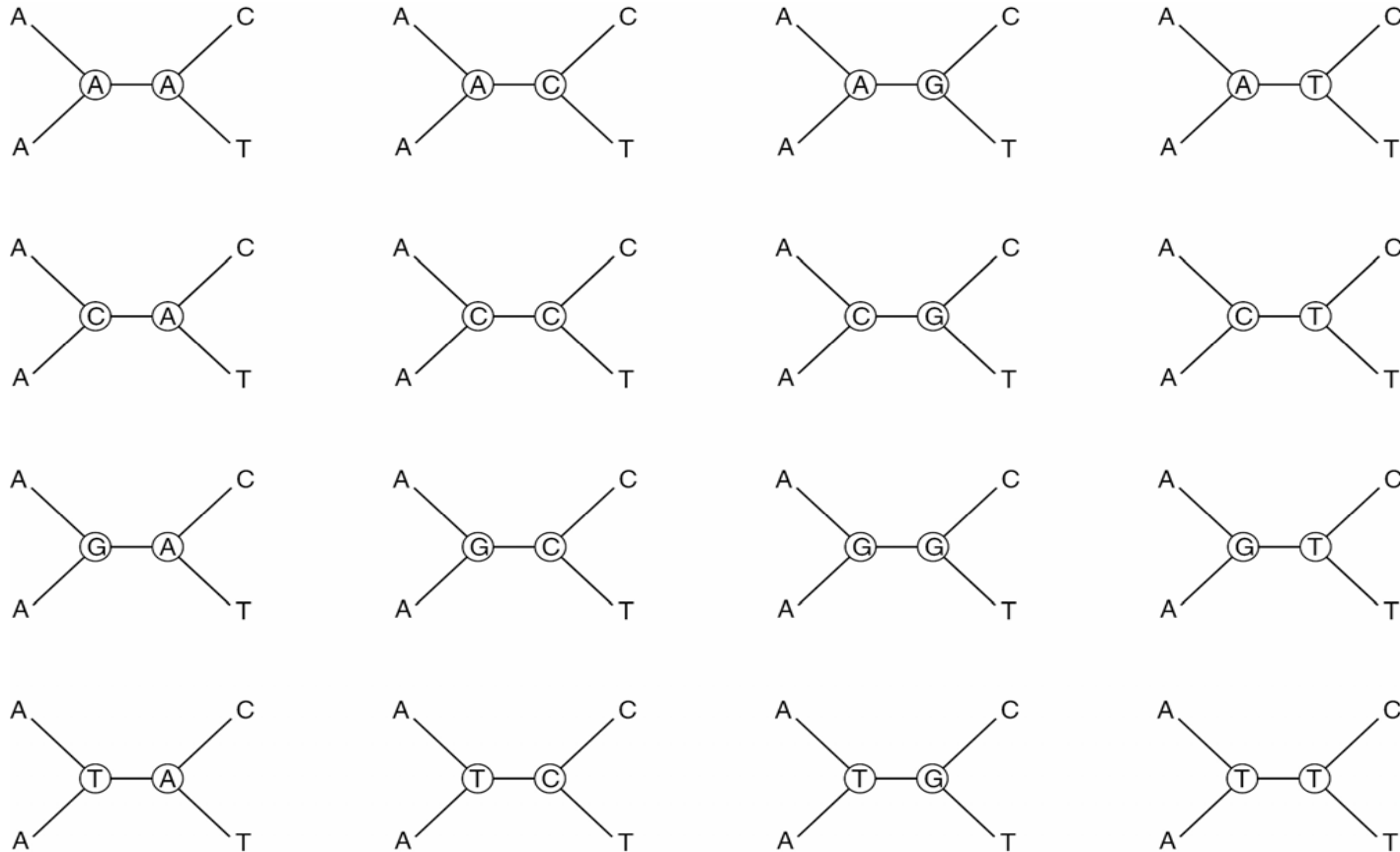
$P_{AA}(v_2)$

$P_{AC}(v_3)$

$P_{CT}(v_4)$

$P_{CC}(v_5)$

Brute force approach would be to calculate L_k for all 16 combinations of ancestral states and sum



Likelihood and Bayesian procedures

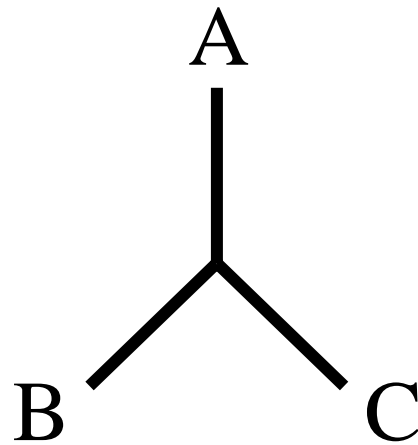
1. very computationally intensive,
2. Use all of the information in the data,
3. Let us estimate the forces of character evolution while estimating trees,
4. Uses models to detect concerted patterns of homoplasy (this is how likelihood based procedures avoid long-branch attraction).

Tree Searching

Parsimony and ML give us ways to deciding whether one tree is fits our data better than another tree, but . . .

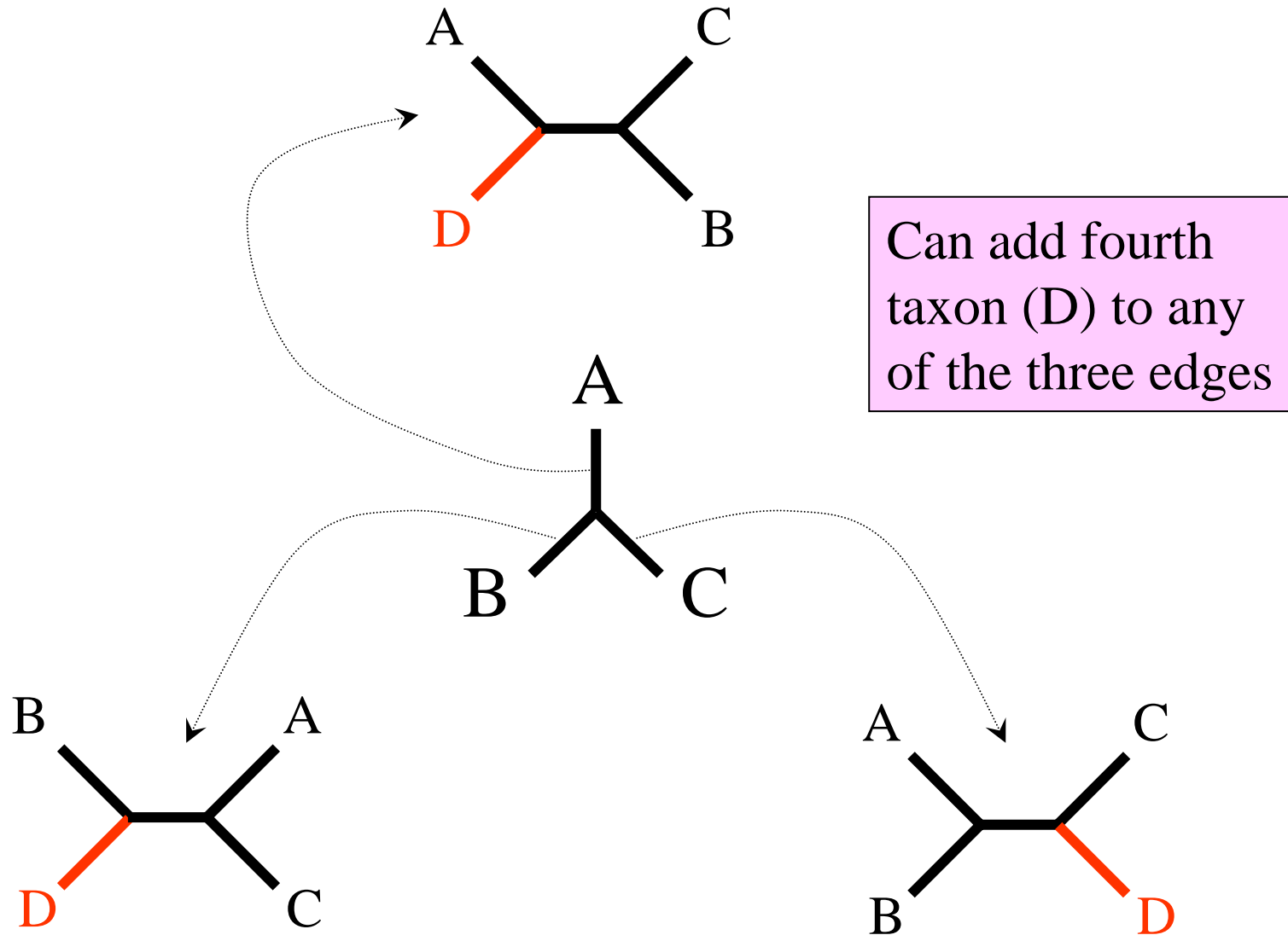
How do we find the best tree?
(or one that is good enough)

Exhaustive Enumeration



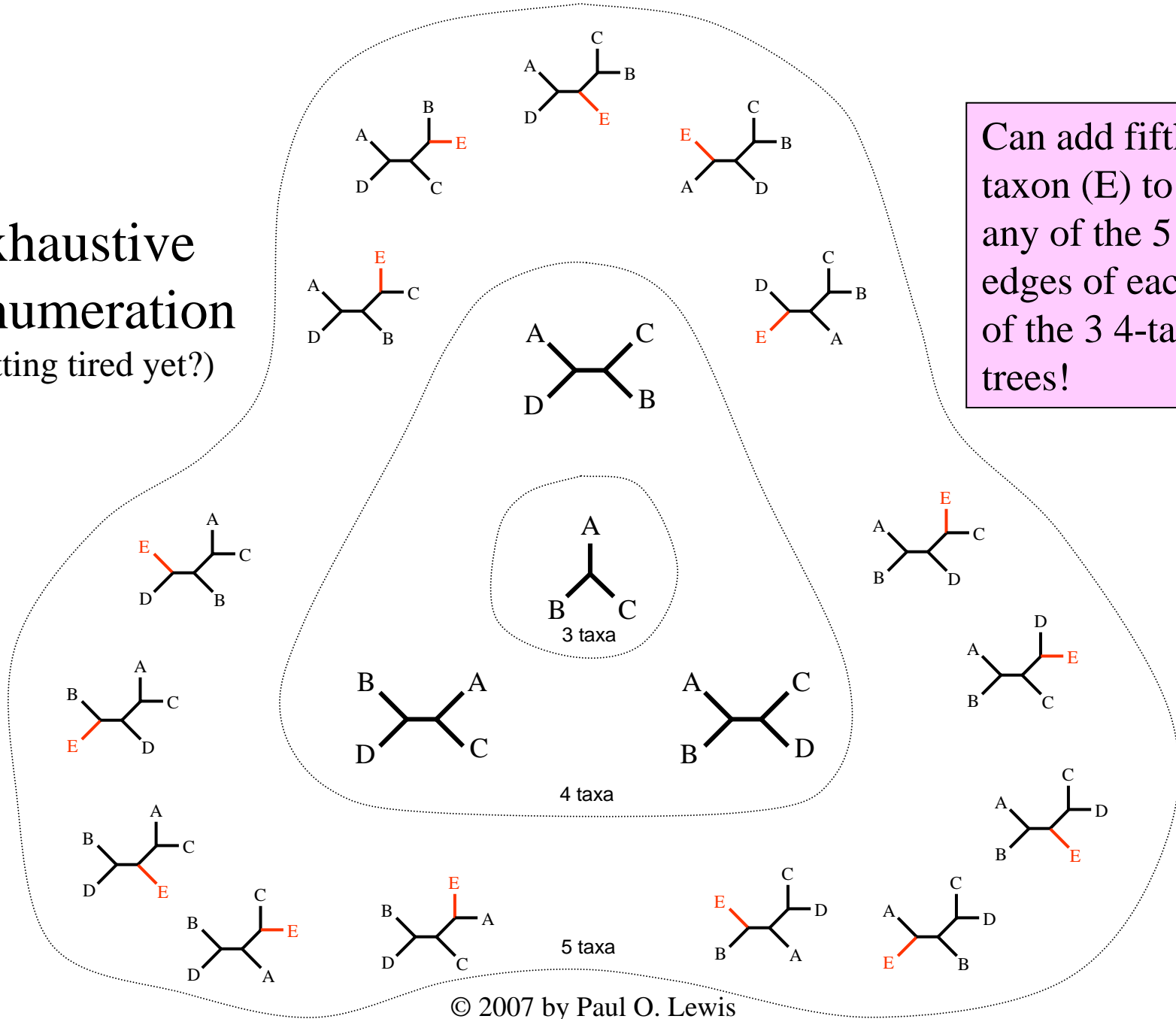
With the first three taxa, create the trivial unrooted tree

Exhaustive Enumeration...



Exhaustive Enumeration (getting tired yet?)

Can add fifth taxon (E) to any of the 5 edges of each of the 3 4-taxon trees!



| Tips | Number of unrooted (binary) trees | |
|------|-------------------------------------|---------------------|
| 4 | 3 | |
| 5 | 15 | |
| 6 | 105 | |
| 7 | 945 | |
| 8 | 10,395 | |
| 9 | 135,135 | |
| 10 | 2,027,025 | |
| 11 | 34,459,425 | |
| 12 | 654,729,075 | |
| 13 | 13,749,310,575 | |
| 14 | 316,234,143,225 | |
| 15 | 7,905,853,580,625 | |
| 16 | 213,458,046,676,875 | |
| 17 | 6,190,283,353,629,375 | |
| 18 | 191,898,783,962,510,625 | |
| 19 | 6,332,659,870,762,850,625 | |
| 20 | 22,164,309,5476,699,771,875 | |
| 21 | 8,200,794,532,637,891,559,375 | |
| 22 | 319,830,986,772,877,770,815,625 | |
| 23 | 13,113,070,457,687,988,603,440,625 | > 21 moles of trees |
| 24 | 563,862,029,680,583,509,947,946,875 | |

For N taxa:

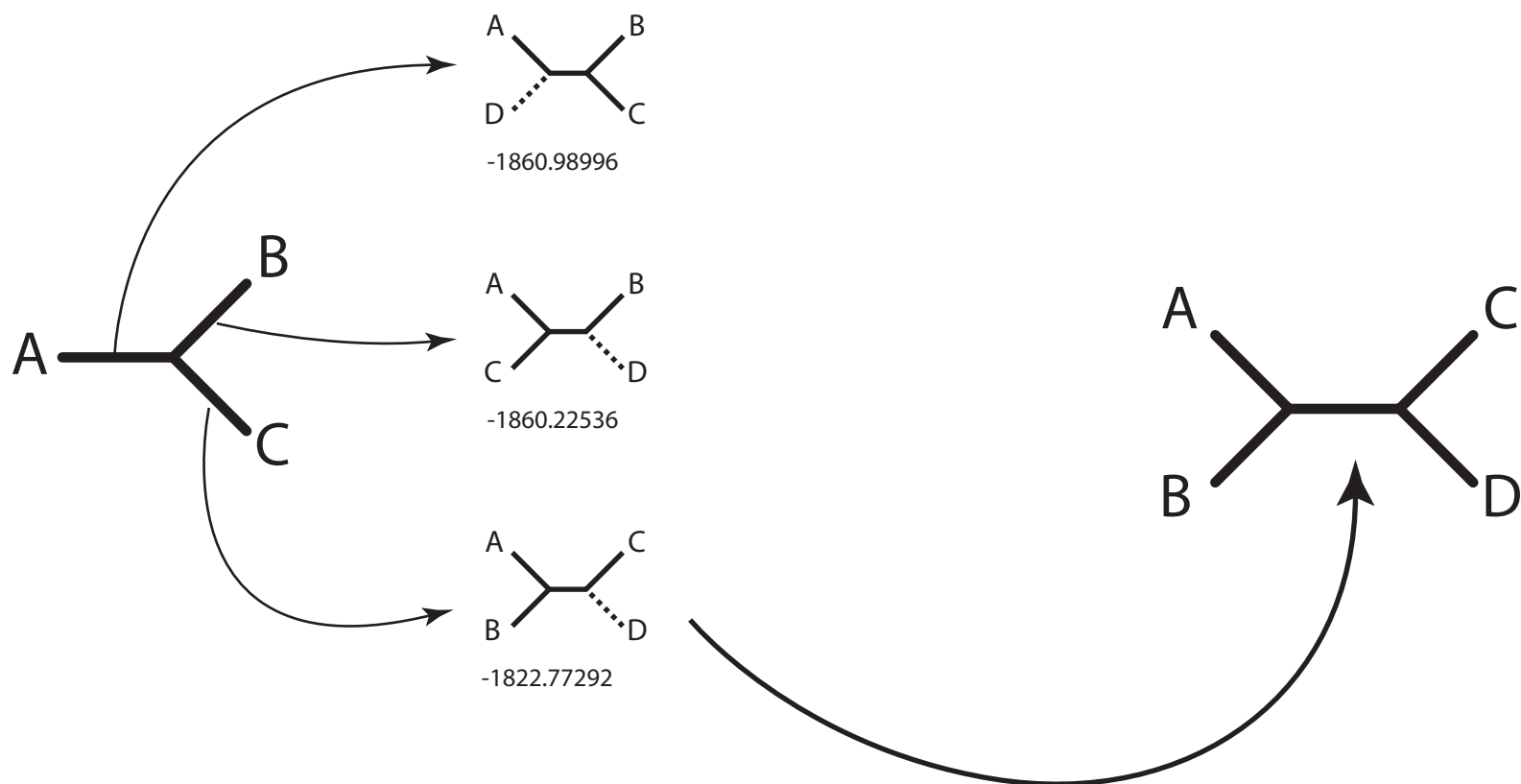
$$\# \text{ unrooted, binary trees} = \prod_{i=3}^{N-1} (2i - 3)$$

$$= \prod_{i=4}^N (2i - 5)$$

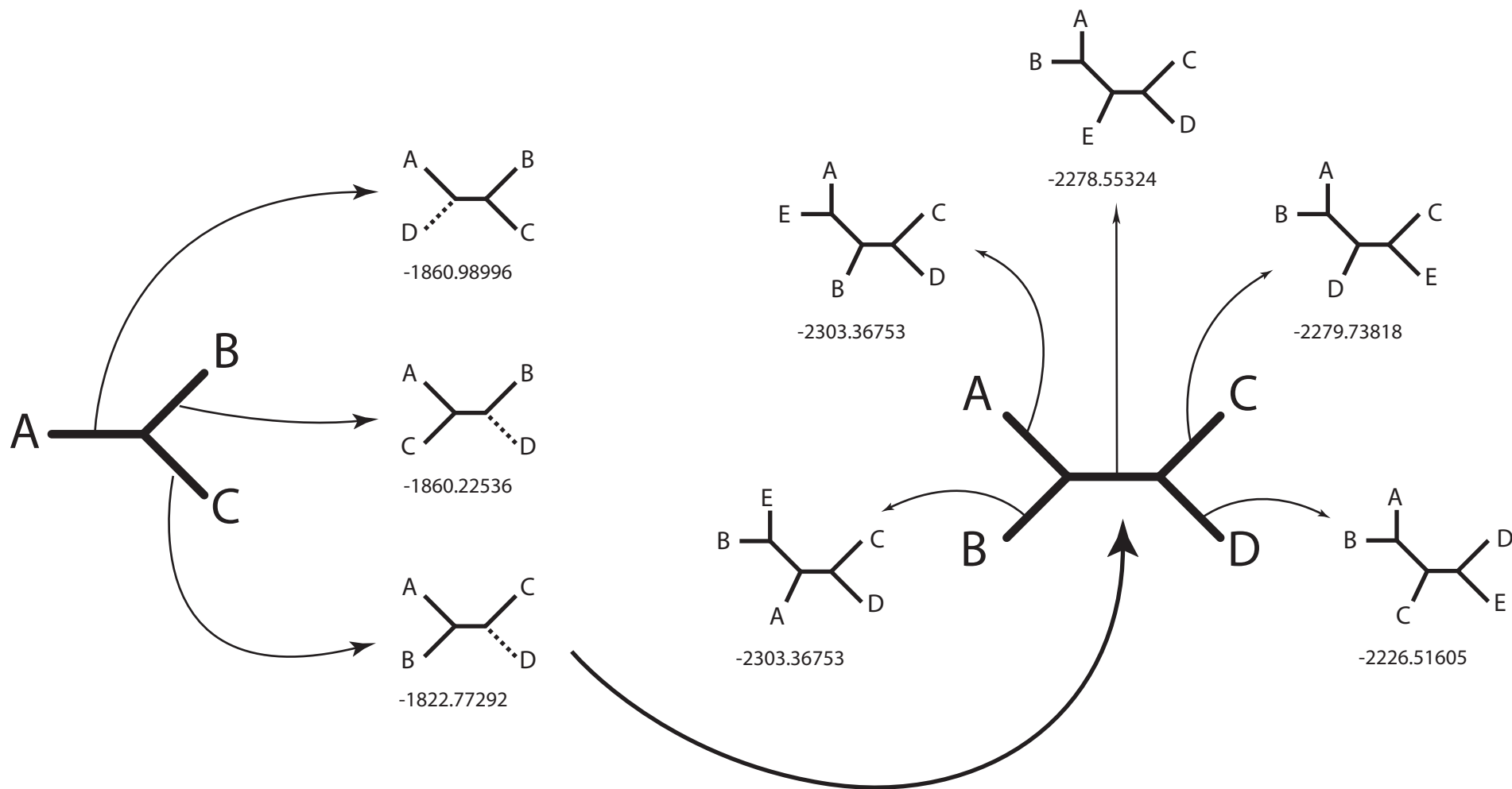
$$\# \text{ rooted, binary trees} = \prod_{i=3}^N (2i - 3)$$

$$= (2N - 3)(\# \text{ unrooted, binary trees})$$

Stepwise addition



Stepwise addition



Is stepwise addition guaranteed to find the best tree?

| | 1 | 2 | 3 | 4 | 5 |
|--------|---|---|---|---|---|
| taxonA | A | A | A | A | A |
| taxonB | A | C | C | A | C |
| taxonC | C | C | C | T | T |
| taxonD | C | A | A | C | T |
| taxonE | A | A | A | T | C |

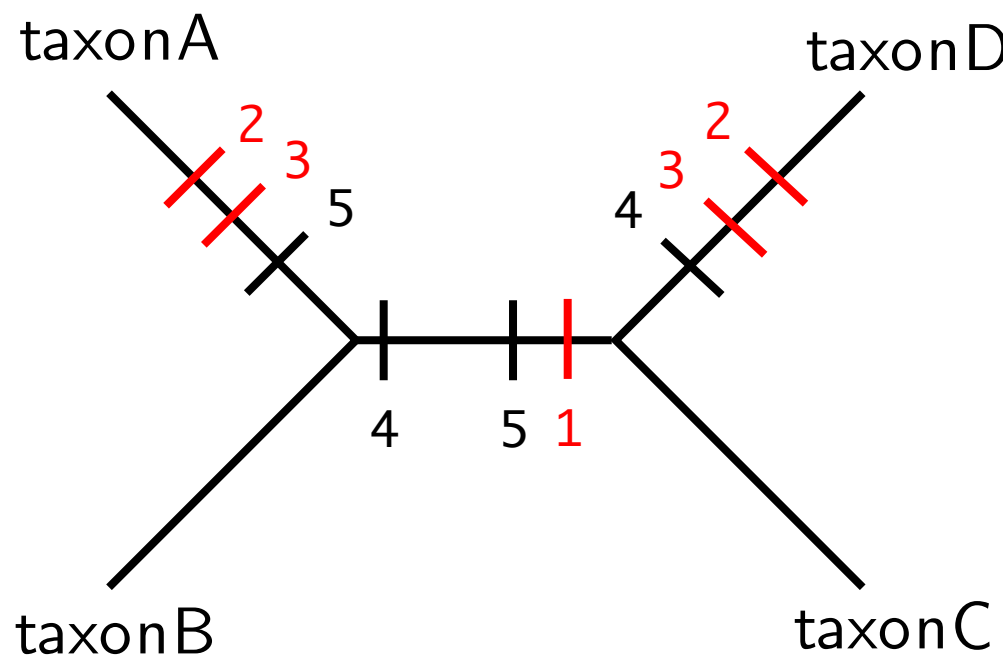
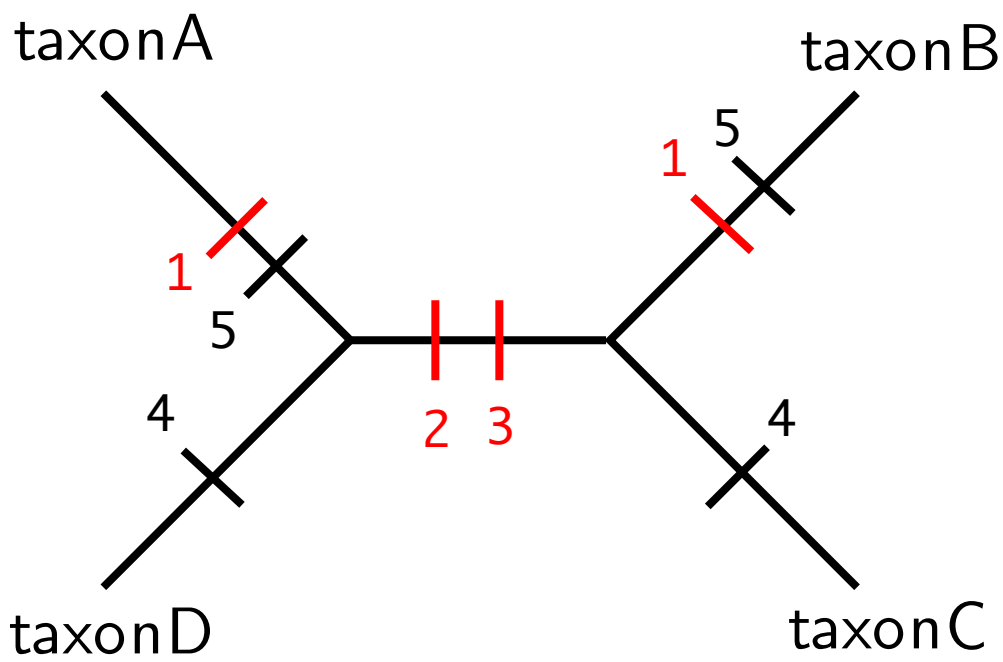
First step of stepwise addition

| | 1 | 2 | 3 | 4 | 5 |
|--------|---|---|---|---|---|
| taxonA | A | A | A | A | A |
| taxonB | A | C | C | A | C |
| taxonC | C | C | C | T | T |
| taxonD | C | A | A | C | T |

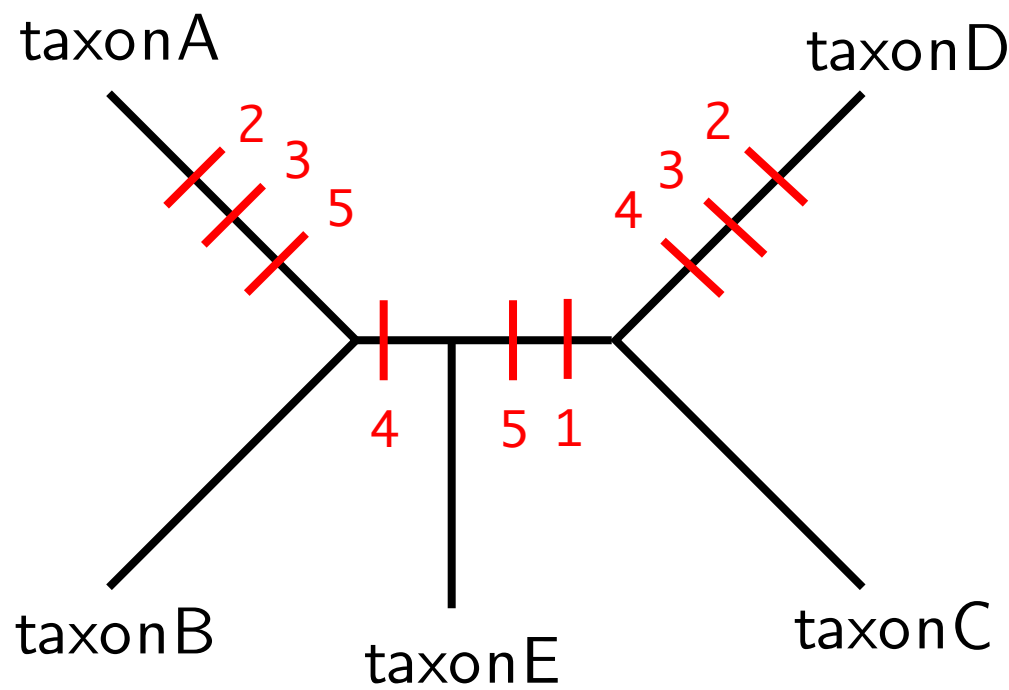
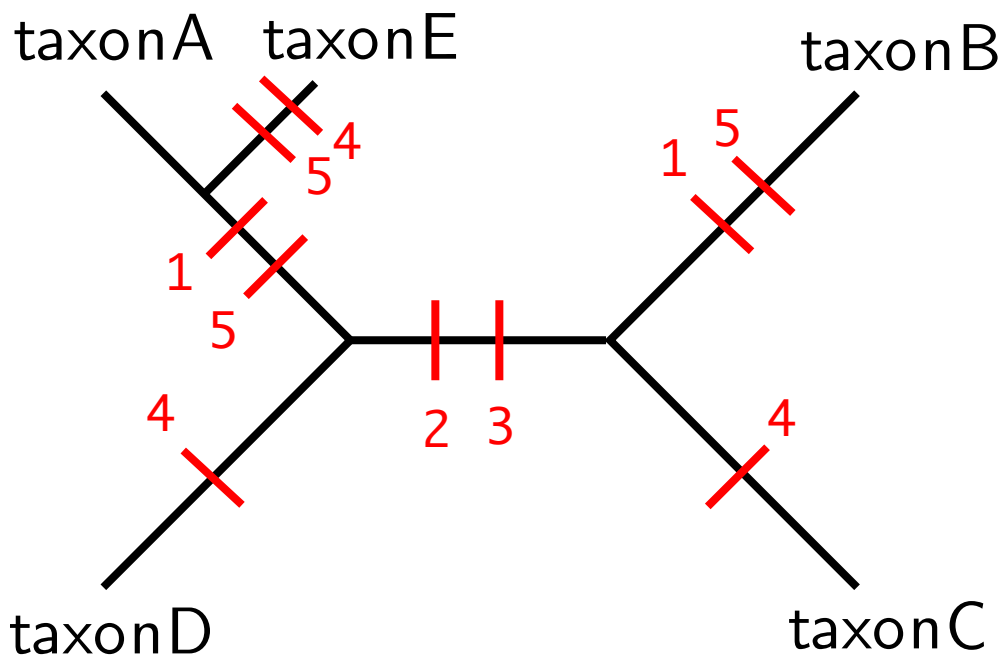
First step of stepwise addition

| | 1 | 2 | 3 | 4 | 5 | |
|---------------------|---|---|---|---|---|----|
| taxonA | A | A | A | A | A | |
| taxonB | A | C | C | A | C | |
| taxonC | C | C | C | T | T | |
| taxonD | C | A | A | C | T | |
| tree (A, B, (C, D)) | 1 | 2 | 2 | 2 | 2 | 9 |
| tree (A, C, (B, D)) | 2 | 2 | 2 | 2 | 2 | 10 |
| tree (A, D, (B, C)) | 2 | 1 | 1 | 2 | 2 | 8 |

| | 1 | 2 | 3 | 4 | 5 |
|--------|---|---|---|---|---|
| taxonA | A | A | A | A | A |
| taxonB | A | C | C | A | C |
| taxonC | C | C | C | T | T |
| taxonD | C | A | A | C | T |



| | 1 | 2 | 3 | 4 | 5 |
|--------|---|---|---|---|---|
| taxonA | A | A | A | A | A |
| taxonB | A | C | C | A | C |
| taxonC | C | C | C | T | T |
| taxonD | C | A | A | C | T |
| taxonE | A | A | A | T | C |



Comparison of two five taxon trees

| | 1 | 2 | 3 | 4 | 5 | |
|--------------------------|---|---|---|---|---|----|
| taxonA | A | A | A | A | A | |
| taxonB | A | C | C | A | C | |
| taxonC | C | C | C | T | T | |
| taxonD | C | A | A | C | T | |
| taxonE | A | A | A | T | C | |
| tree ((A, B), E, (C, D)) | 1 | 2 | 2 | 2 | 2 | 9 |
| tree ((A,E), D, (B, C)) | 2 | 1 | 1 | 3 | 3 | 10 |

Stepwise addition

- heuristic – not guaranteed to find the best tree
- Number of trees scored for N taxa :

$$\begin{aligned}\# \text{ trees scored} &= \sum_{i=3}^{N-1} (2i - 3) \\ &= (N - 1)(N - 3)\end{aligned}$$

Thus, stepwise addition is $O(N^2)$. For $N=10$:

$$63 = 3 + 5 + 7 + 9 + 11 + 13 + 15$$

Trying to improve a tree

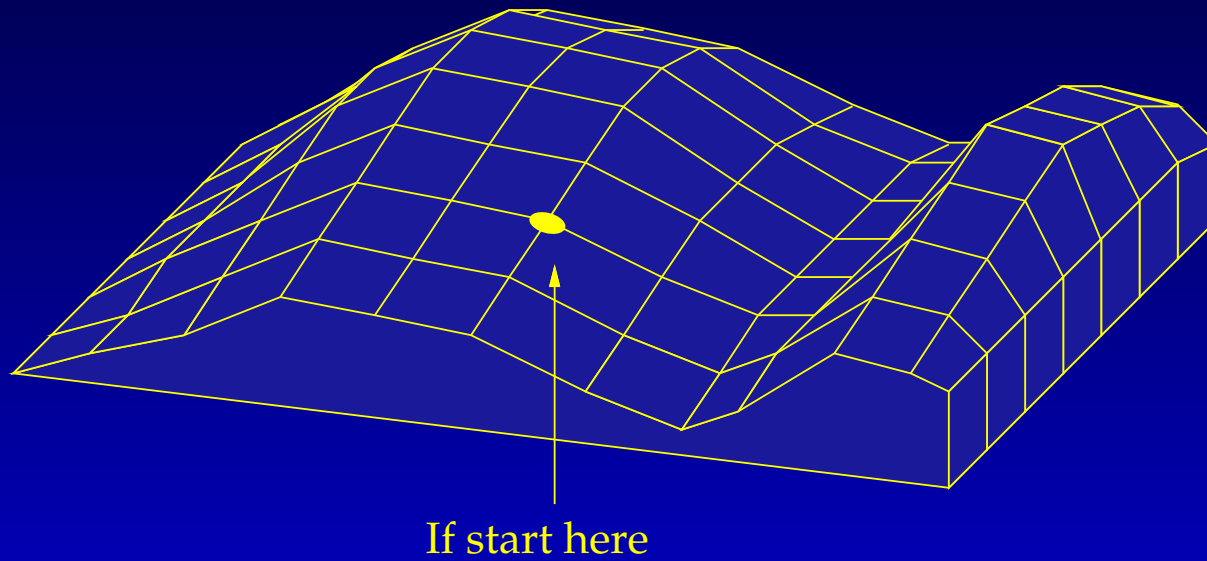
Heuristic hill-climbing searches can work quite well:

1. Start with a tree
2. Score the tree
3. Consider a new tree within the neighborhood of the current tree:
 - (a) Score the new tree.
 - (b) If the new tree has a better score, use it as the “current tree”
 - (c) Stop if there are no other trees within the neighborhood to consider.

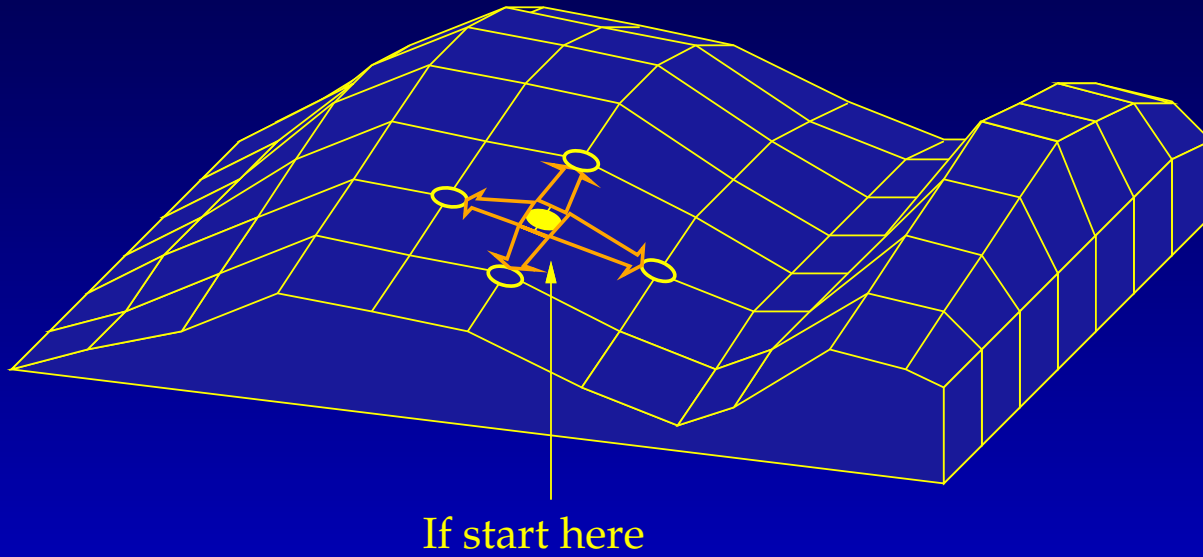
These are **not** guaranteed to find even one of the optimal trees.

The most common way to explore the neighborhood of a tree is to swap the branches of the tree to construct similar trees.

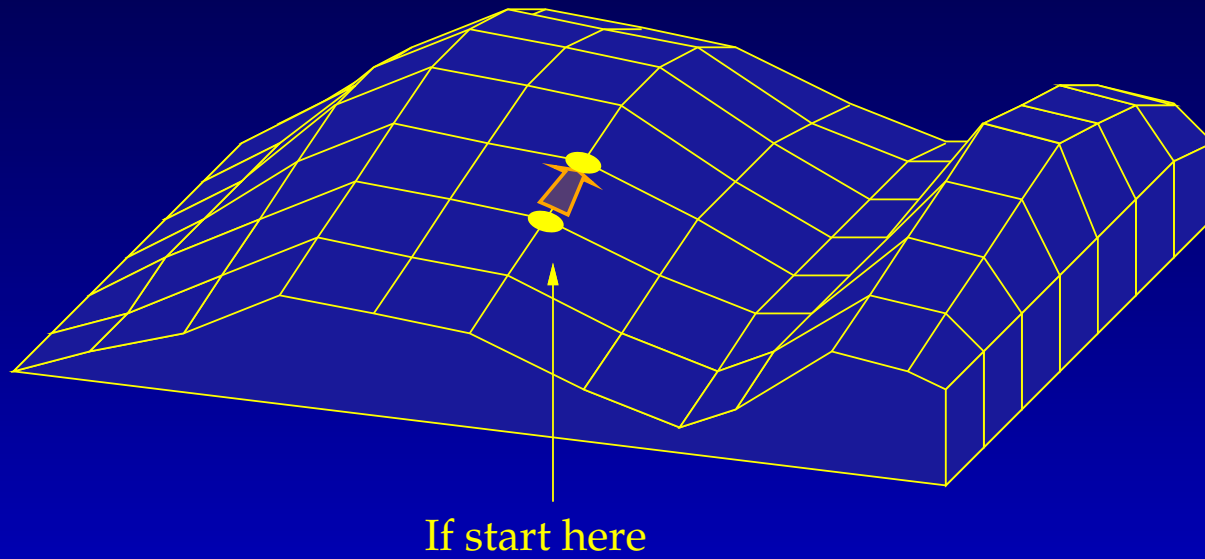
Greedy search for a maximum



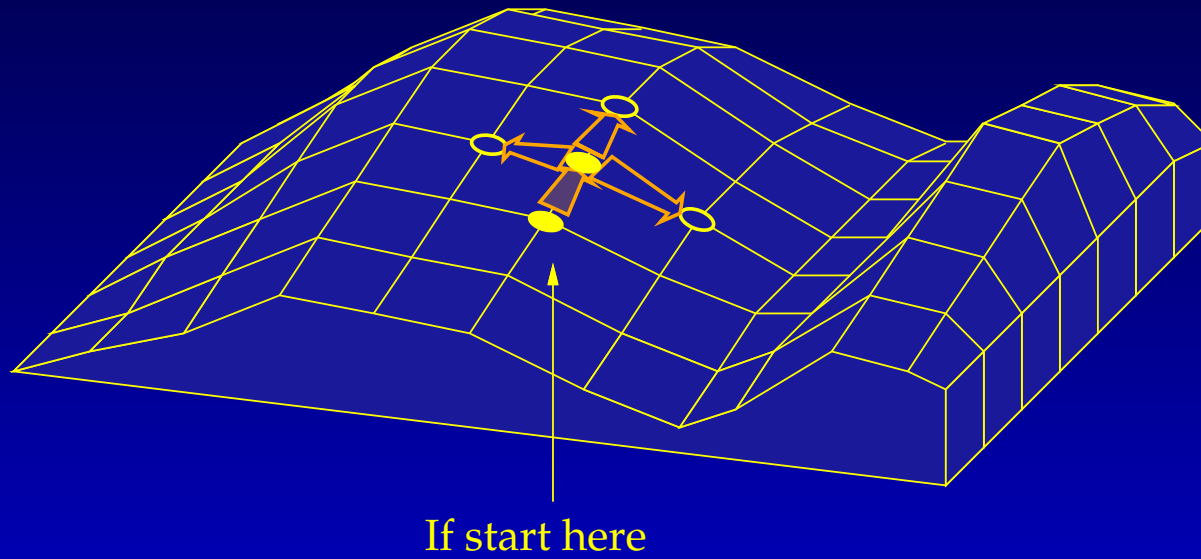
Greedy search for a maximum



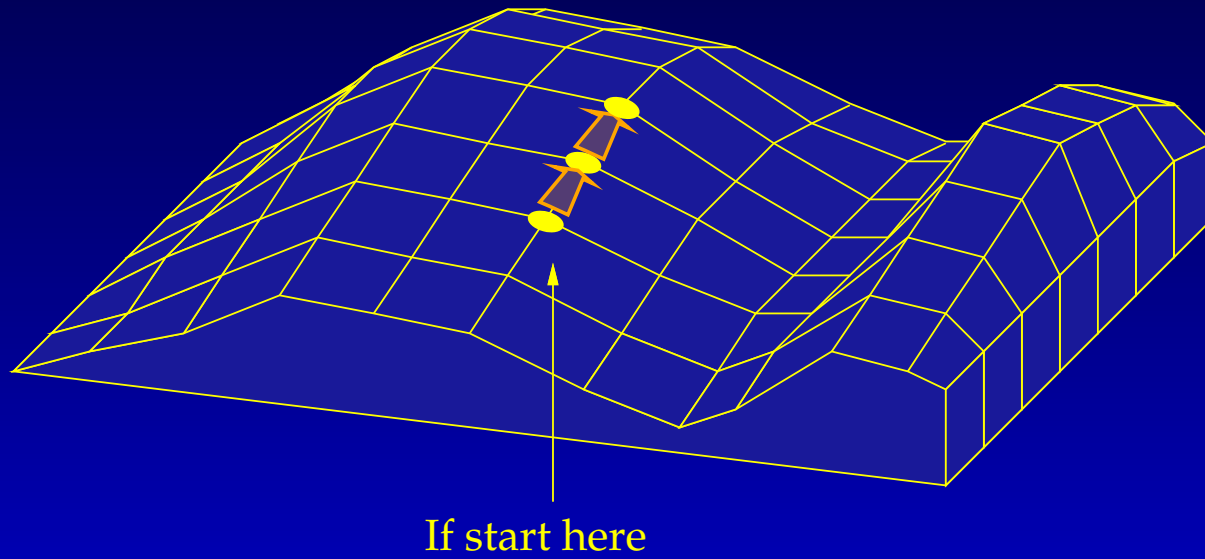
Greedy search for a maximum



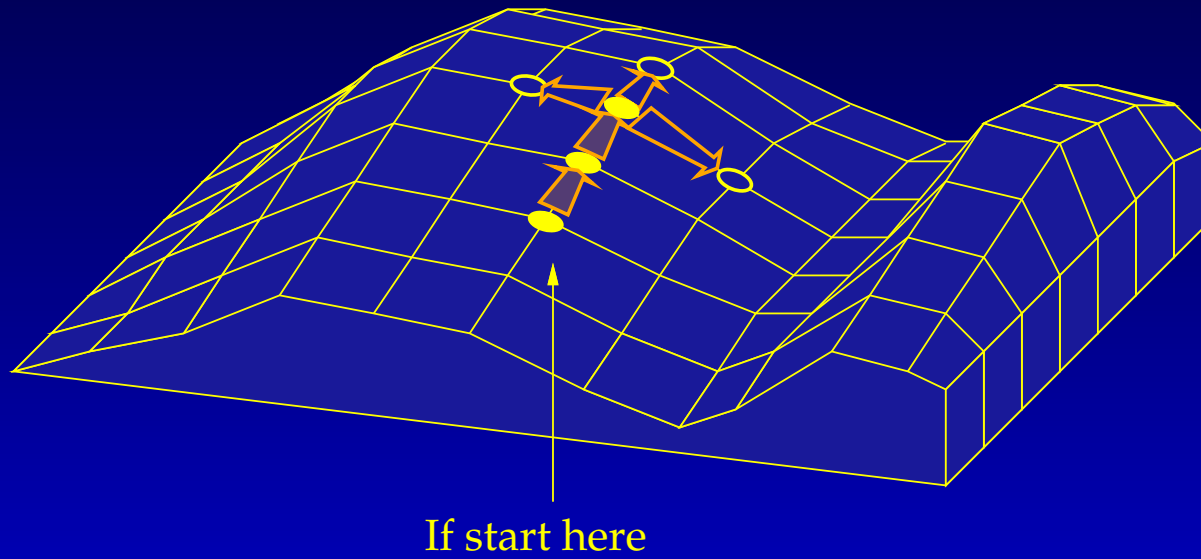
Greedy search for a maximum



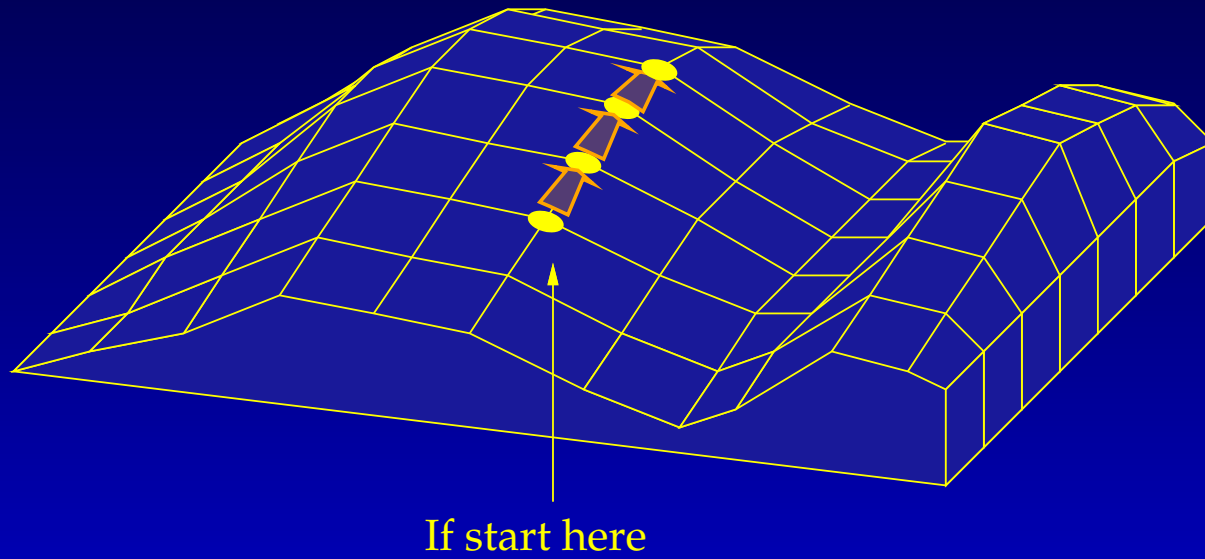
Greedy search for a maximum



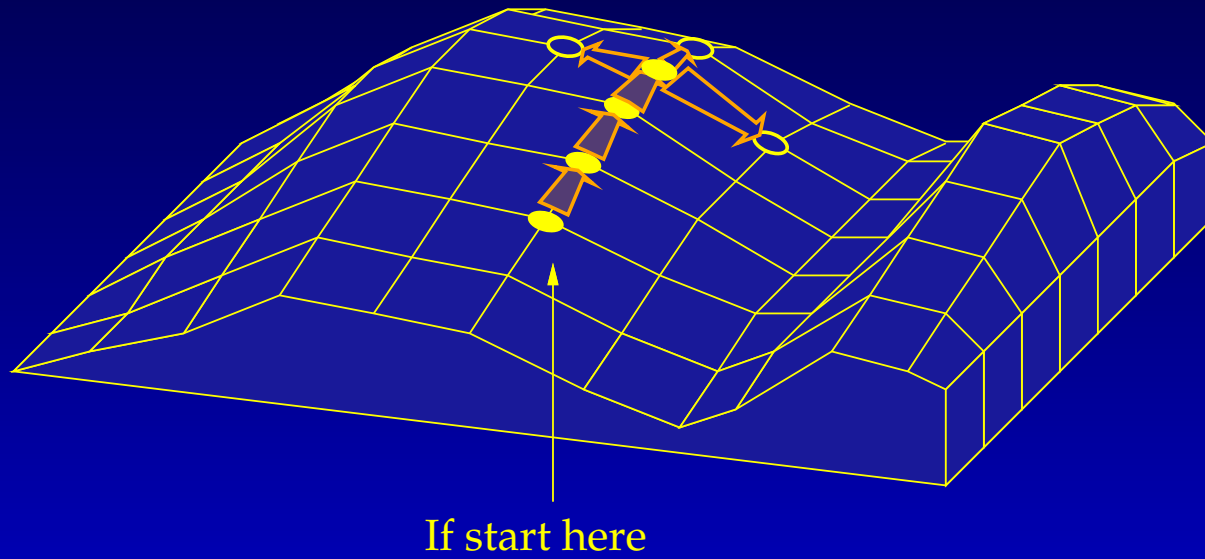
Greedy search for a maximum



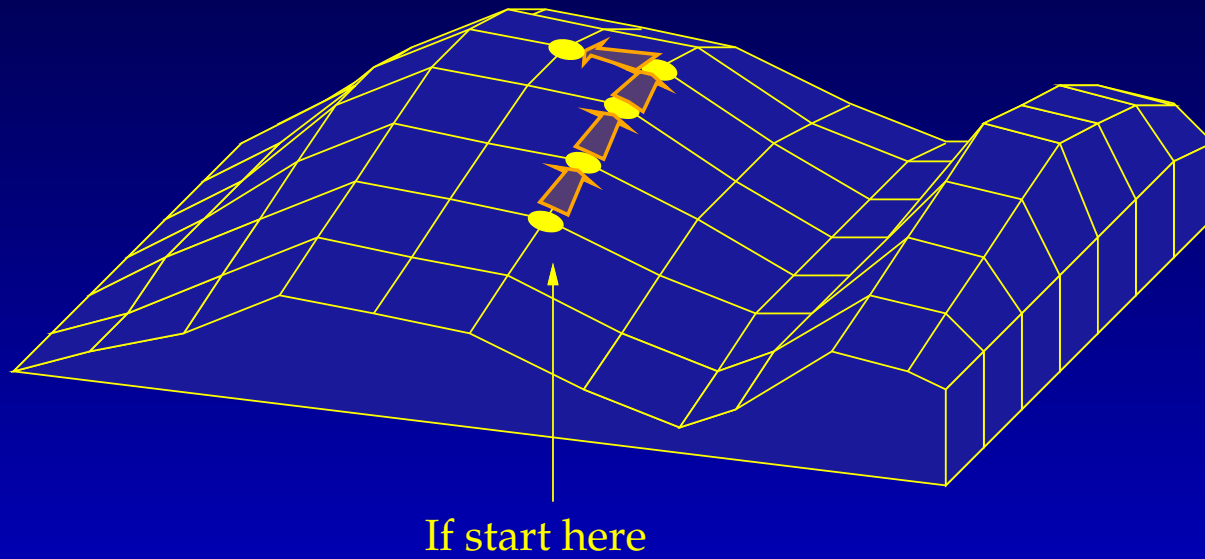
Greedy search for a maximum



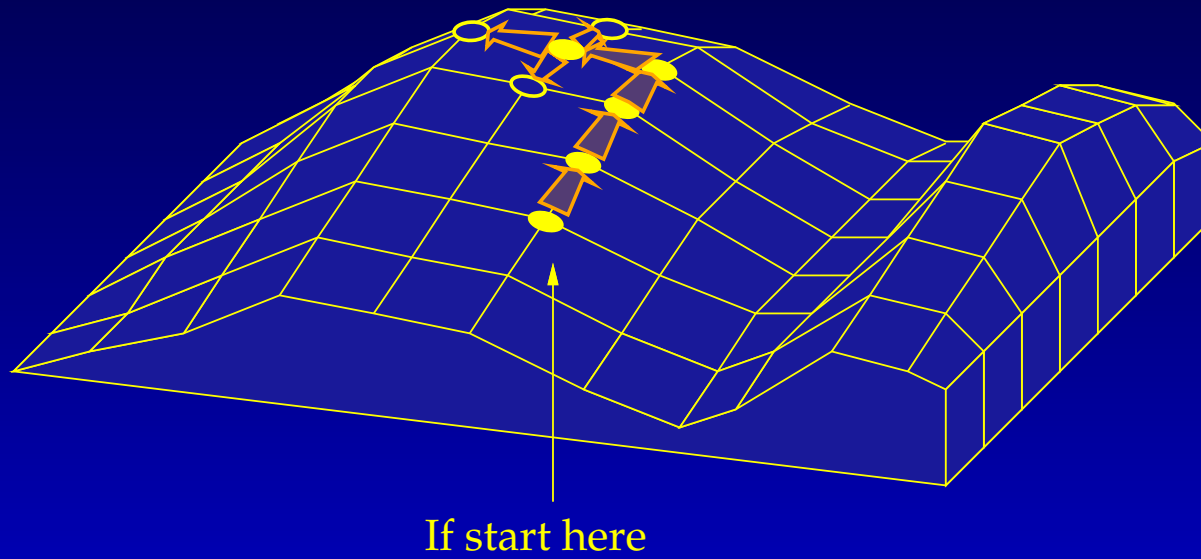
Greedy search for a maximum



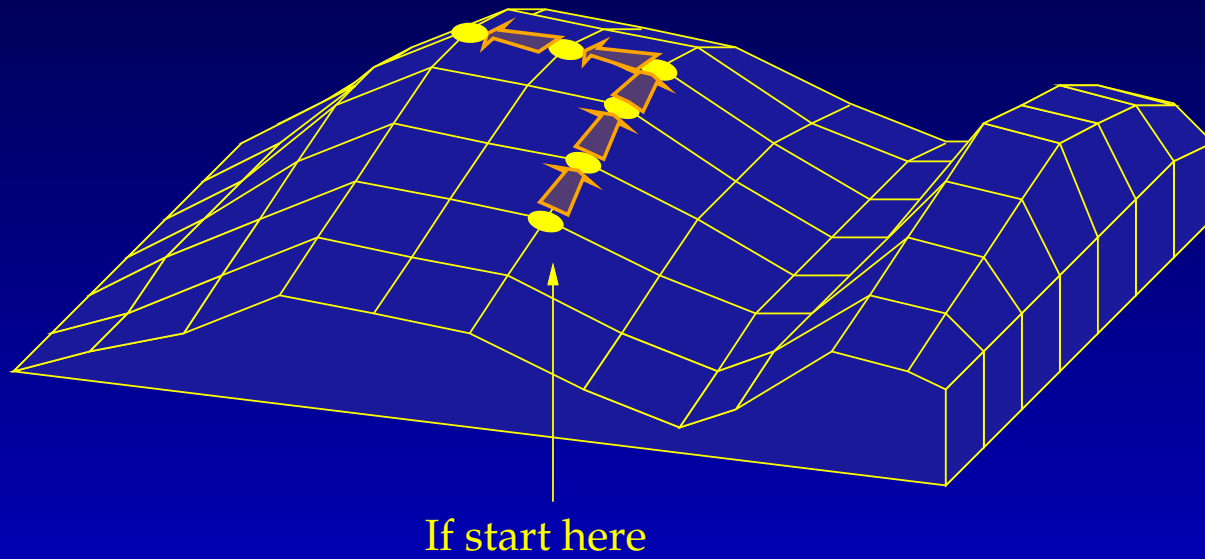
Greedy search for a maximum



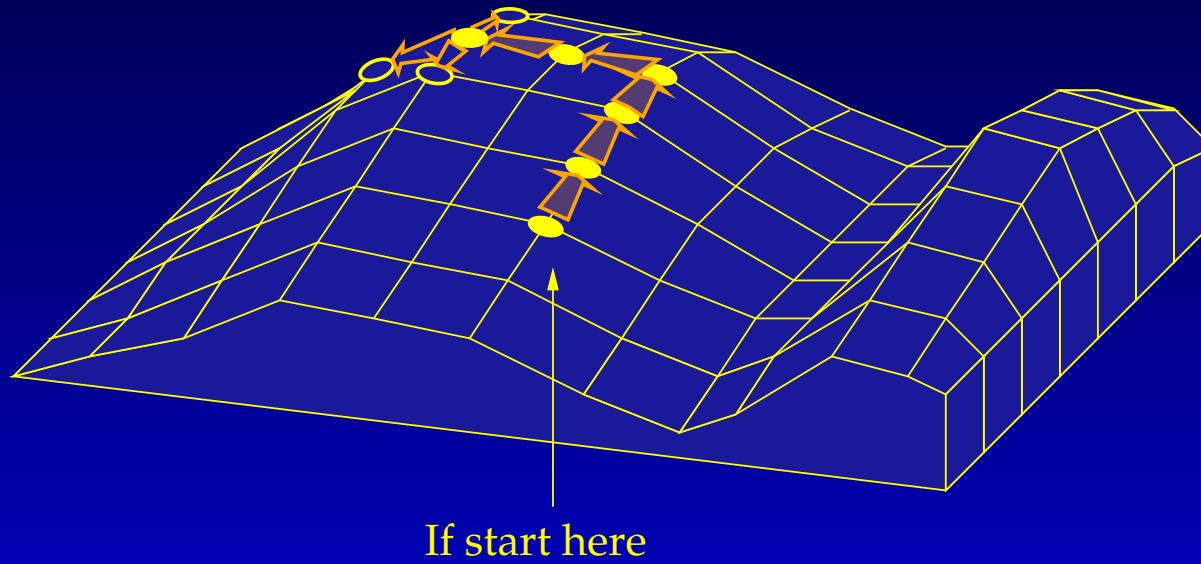
Greedy search for a maximum



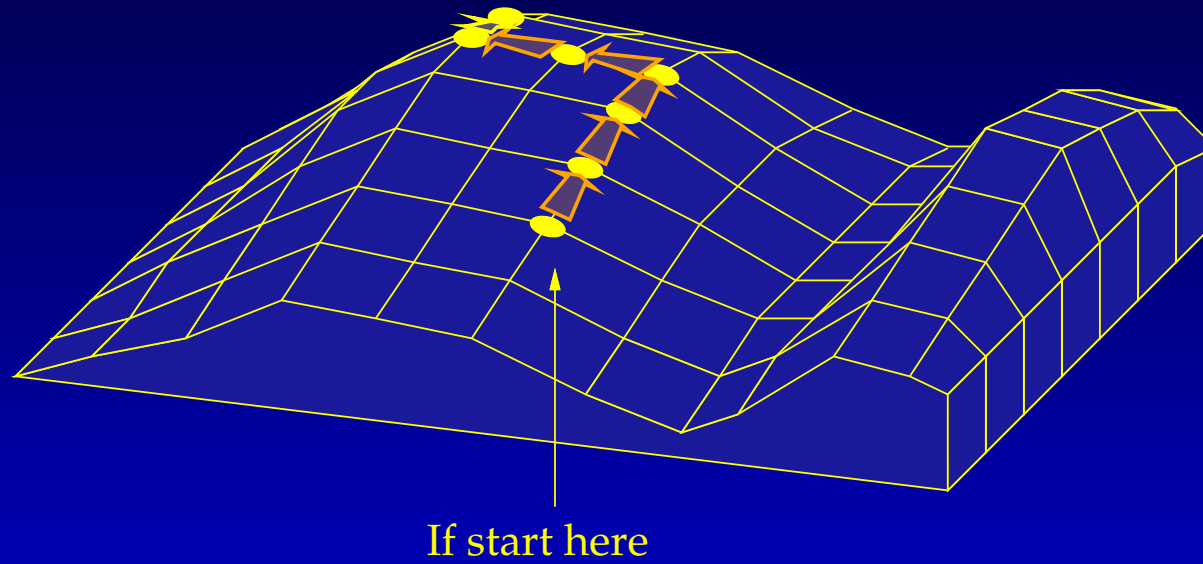
Greedy search for a maximum



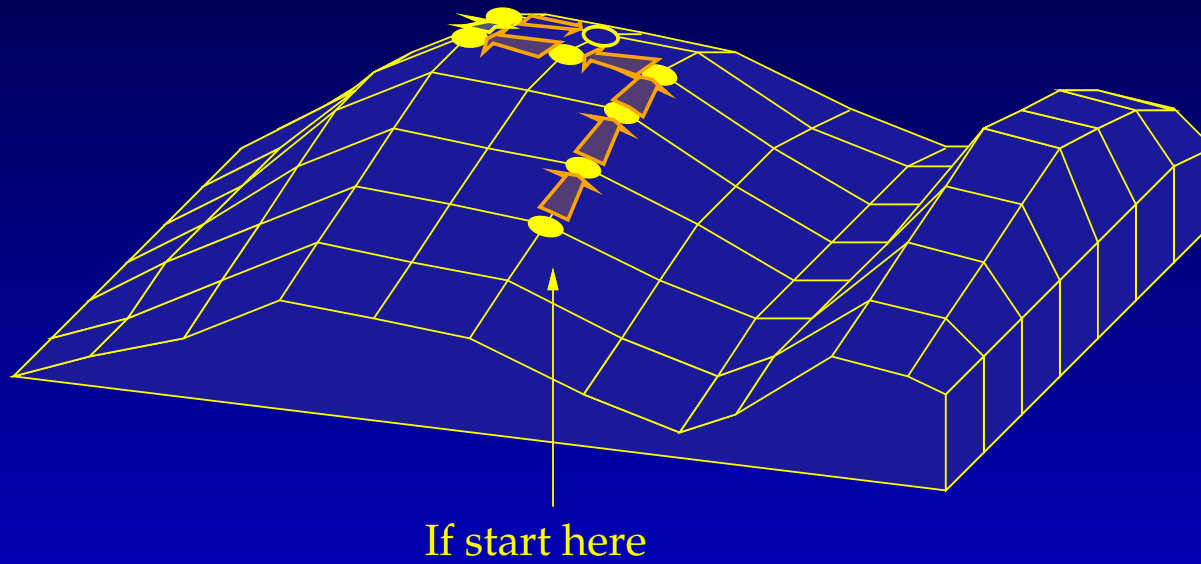
Greedy search for a maximum



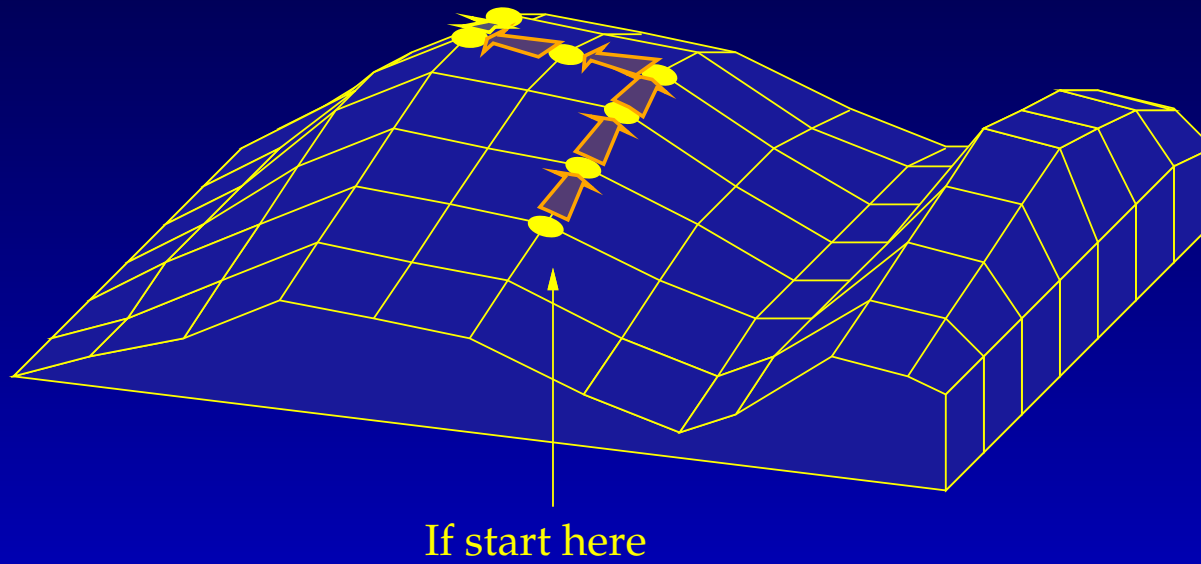
Greedy search for a maximum



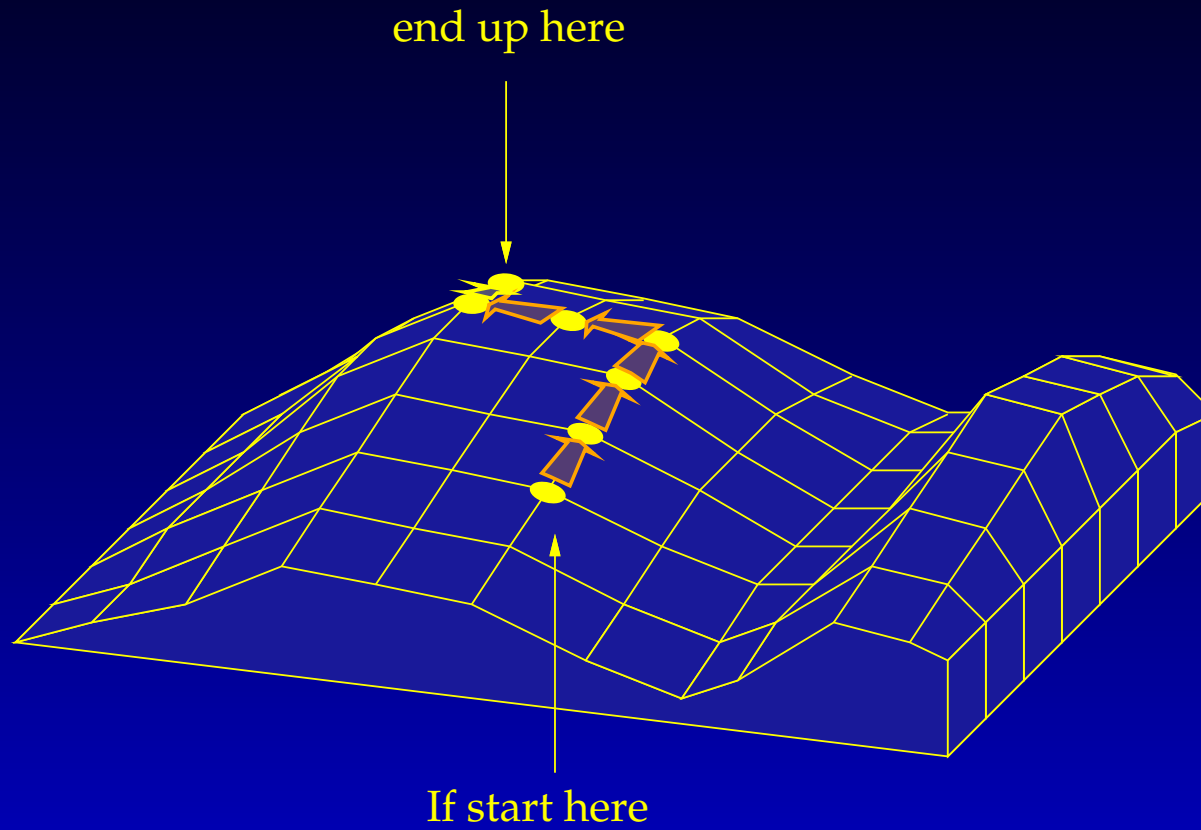
Greedy search for a maximum



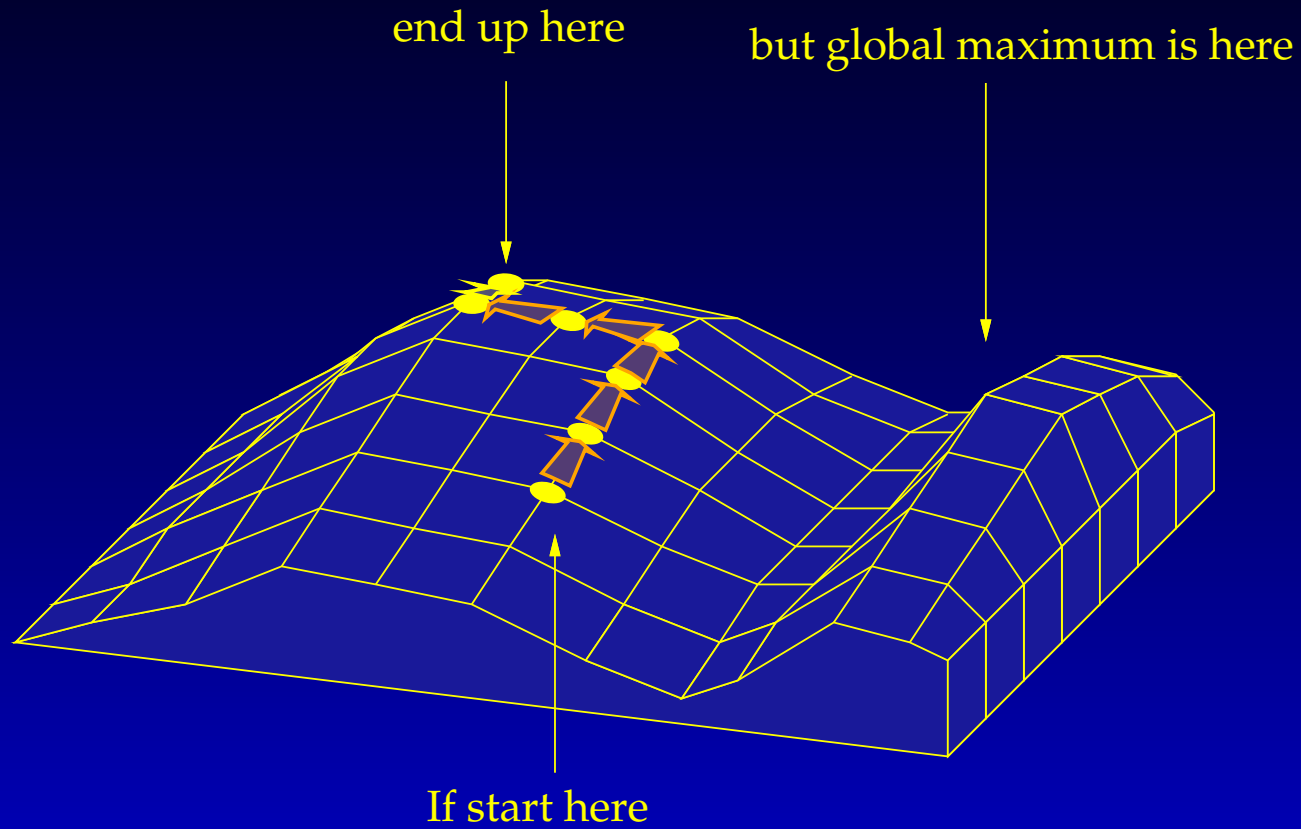
Greedy search for a maximum



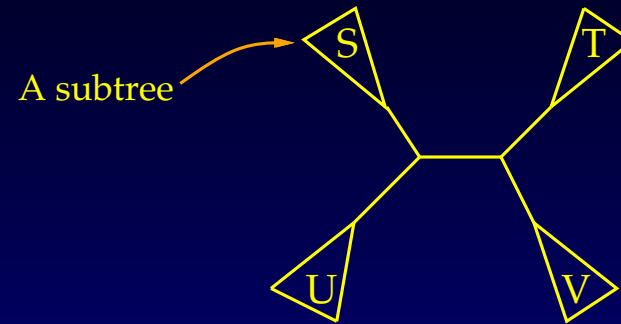
Greedy search for a maximum



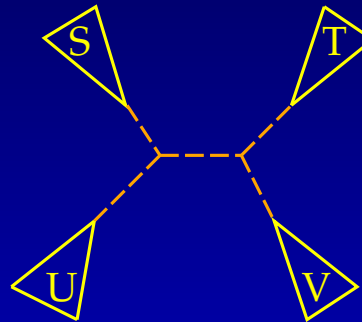
Greedy search for a maximum



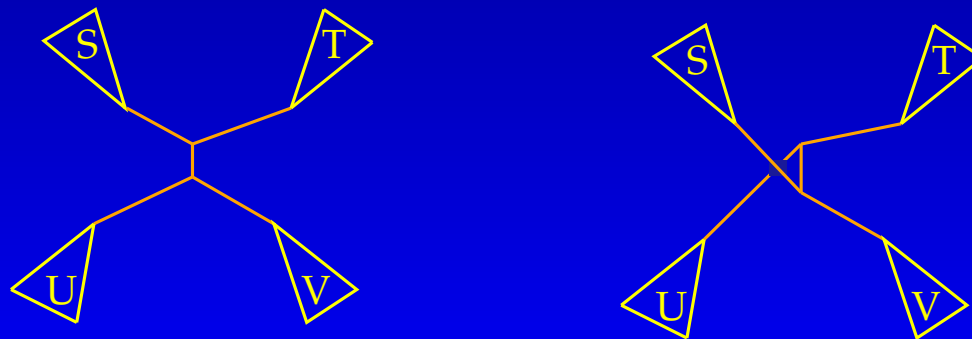
Nearest-neighbor rearrangements



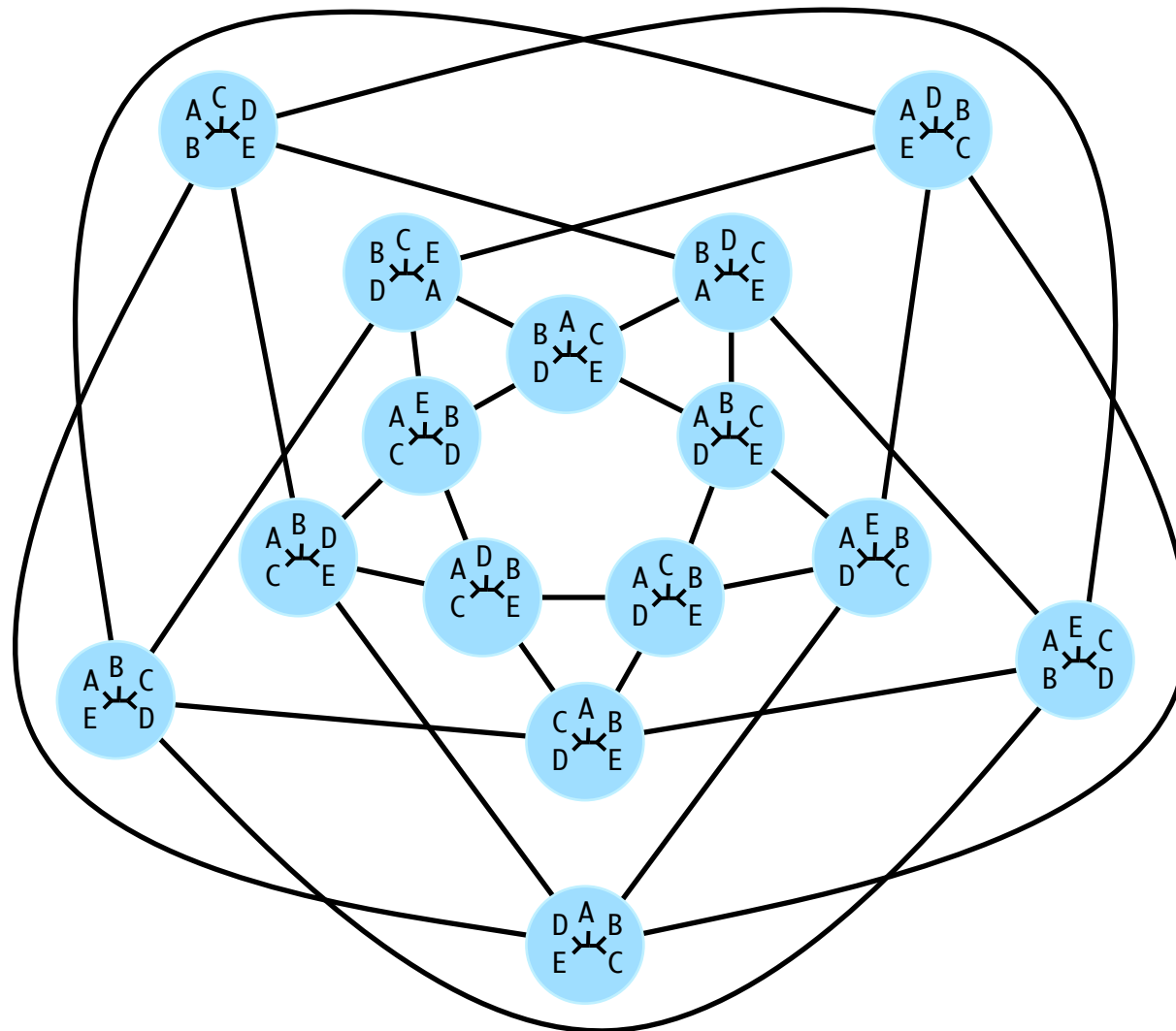
is rearranged by dissolving the connections to an interior branch



and reforming them in one of the two possible alternative ways:



Schoenberg graph – edges connect NNI neighbors



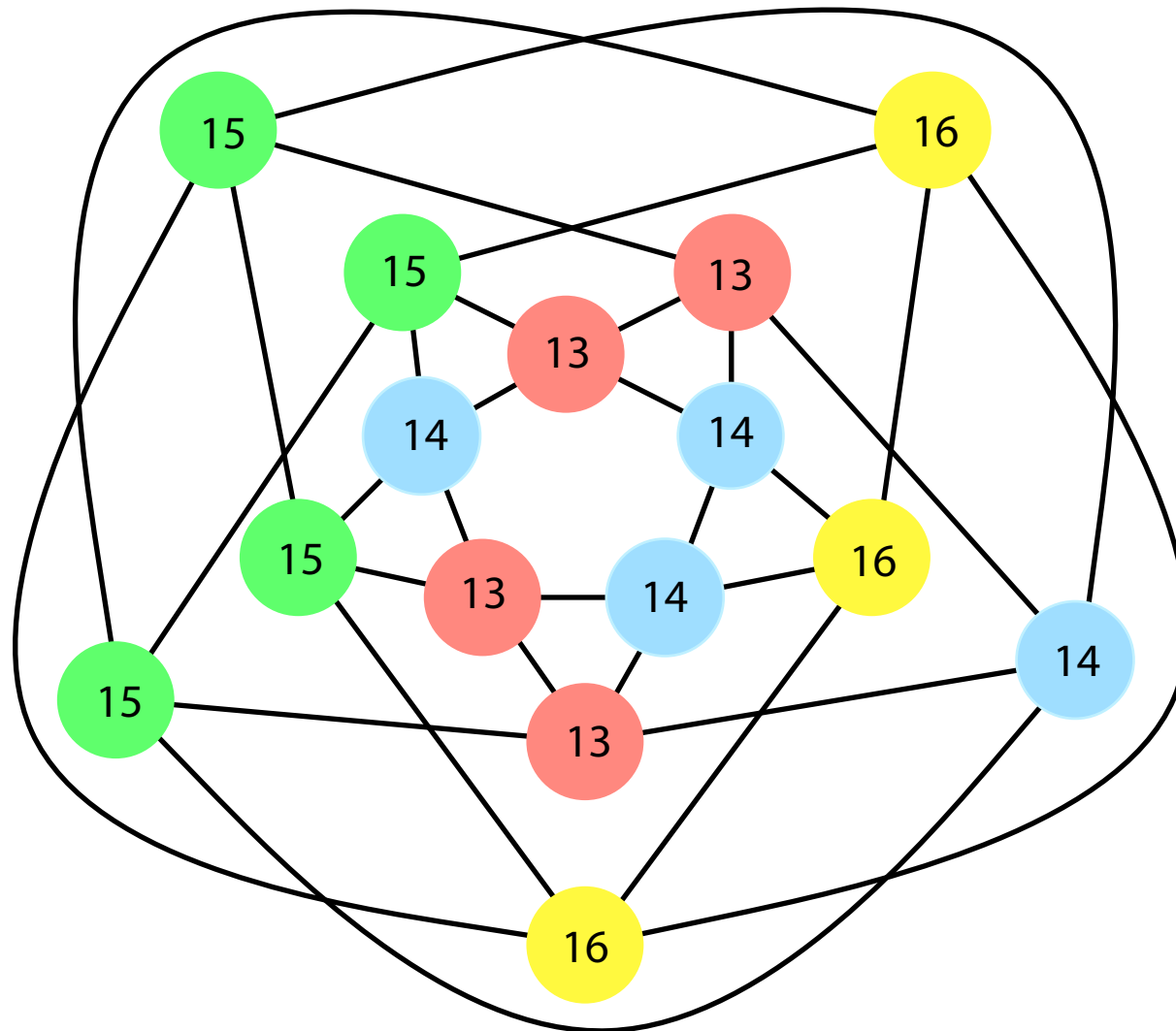
Tree “Islands” possible

An $Op - L$ tree island (*sensu Maddison, 1991*): A set of trees with score $\leq L$ that are connected to each other by Op operations such that you can get from any tree in the set to any other tree by repeated Op changes and all intermediate trees along the path are also members of the set.

The following Schoenberg graph shows the scores of the 15 trees on the following dataset (contrived data by POL):

A ACGCAGGT
B ATGGTGAT
C GCTCACGG
D ACTGTCGT
E GTTCTGAG

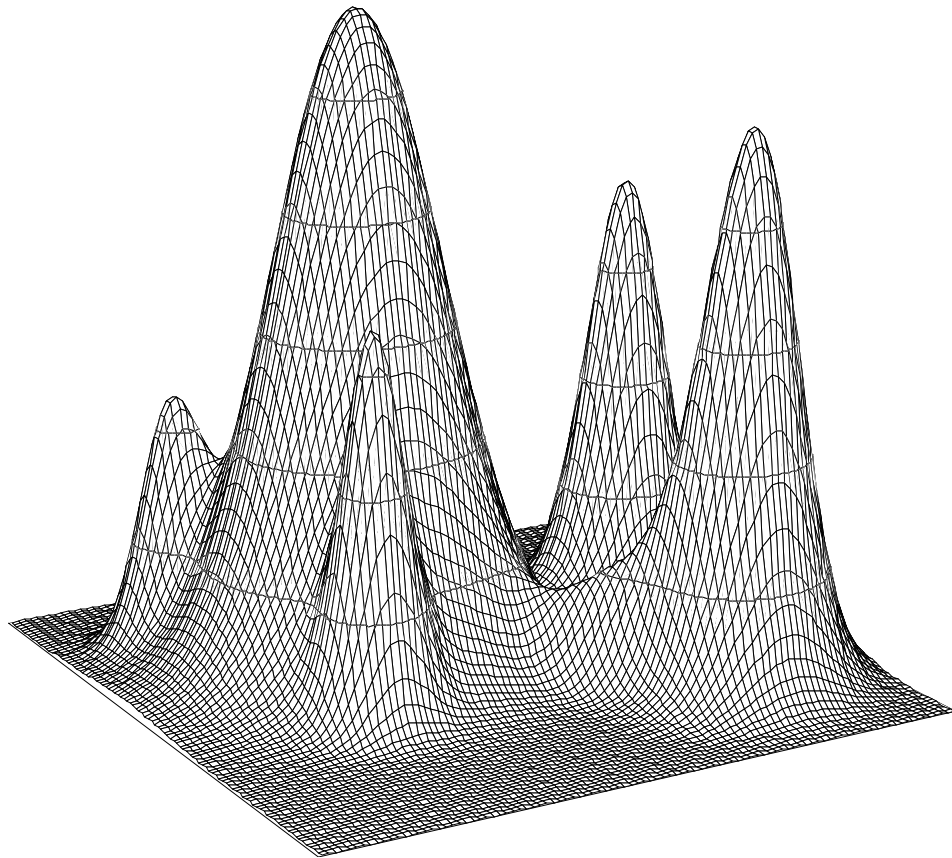
Schoenberg graph with parsimony scores



Tree Islands implications

1. Islands can be larger than 1 tree – we must consider ties if we want to find all trees that optimize the score.
2. Swapping to completion on all optimal trees found in a search is **not** guaranteed to succeed.
3. The delimitation of an island depends on tree changing operation used.

Heuristics explore “Tree Space”

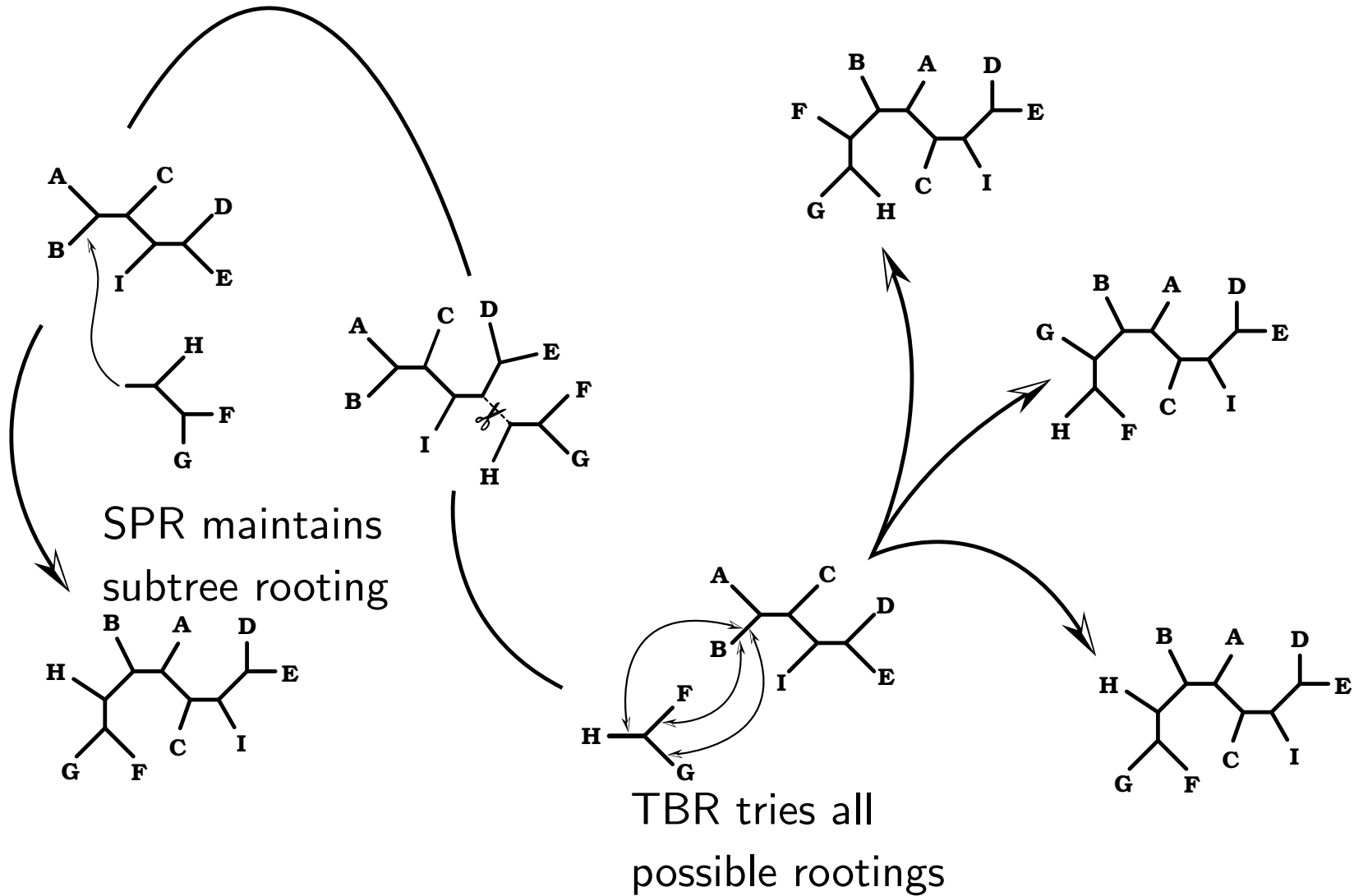


Most commonly used methods are “hill-climbers.”

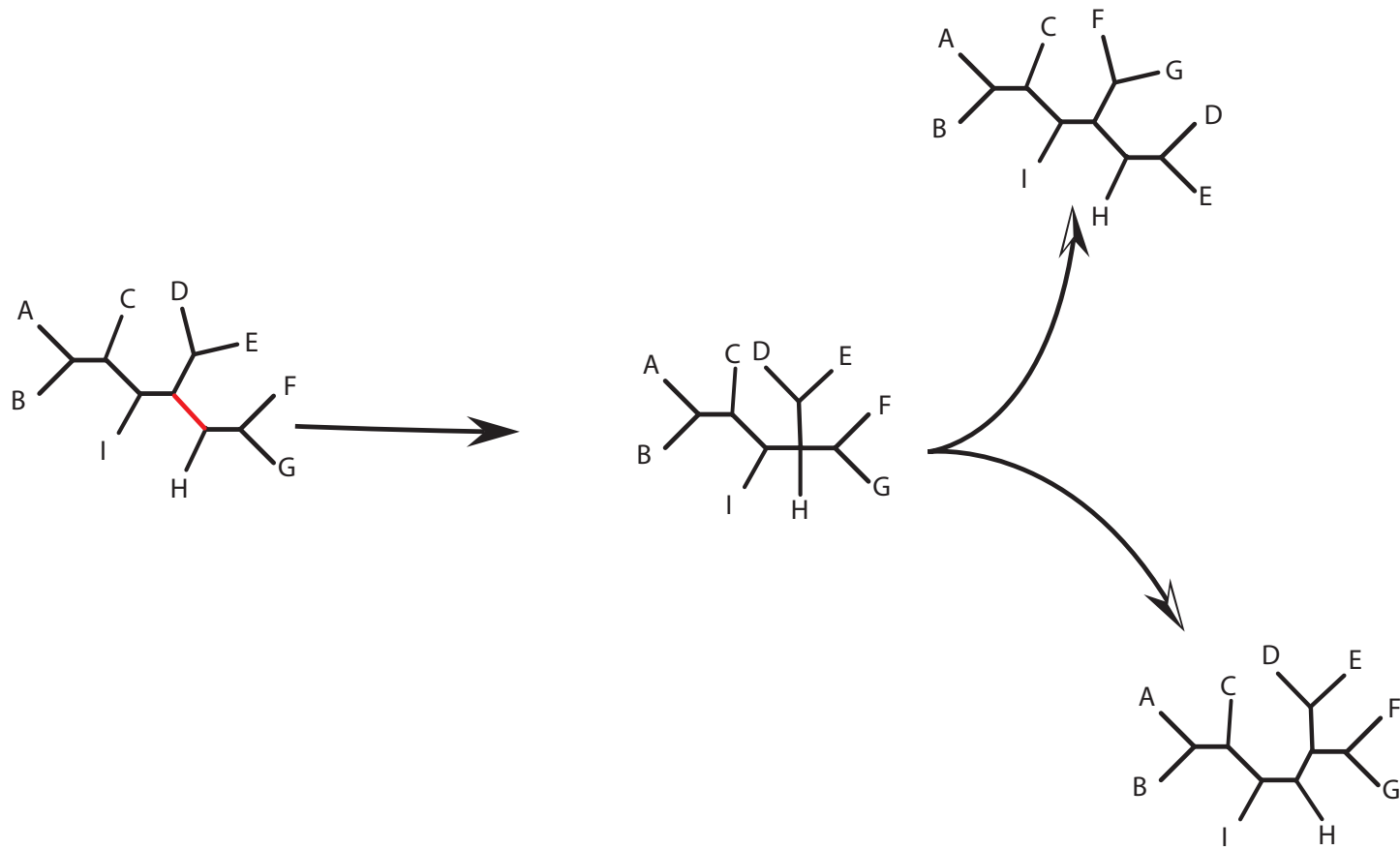
Multiple optima found by repeating searches from different origins.

Severity of the problem of multiple optima depends on step size.

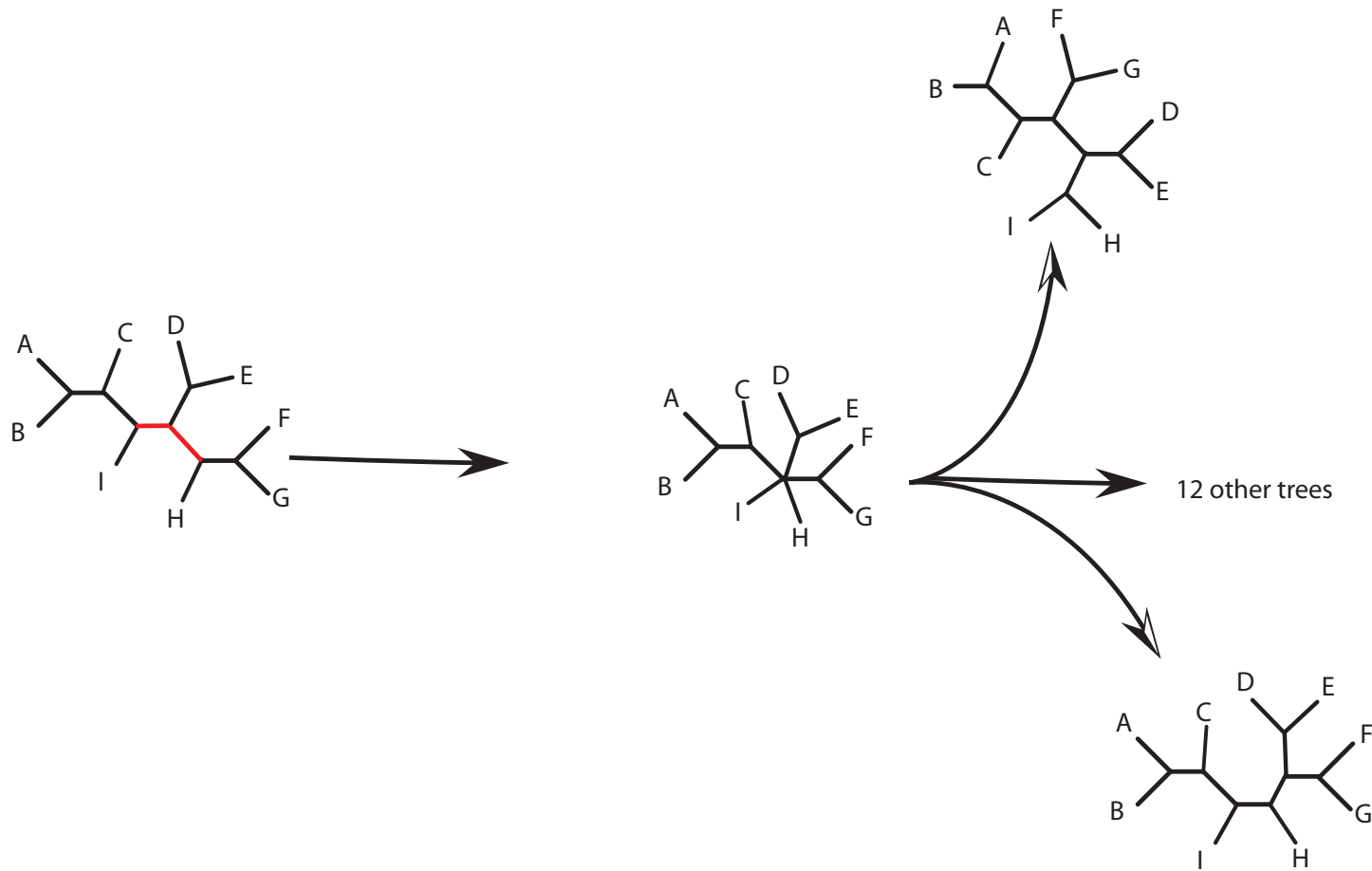
Subtree Pruning Regrafting (SPR) and Tree Bisection Reconnection (TBR)



1-Edge-contract Refine



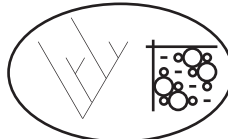
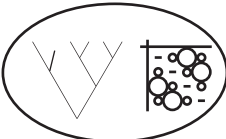
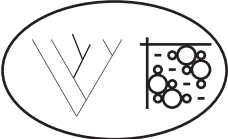
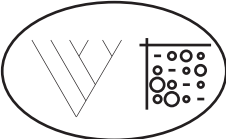
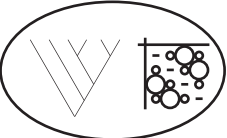
2-Edge-contract Refine



Many other heuristic strategies proposed

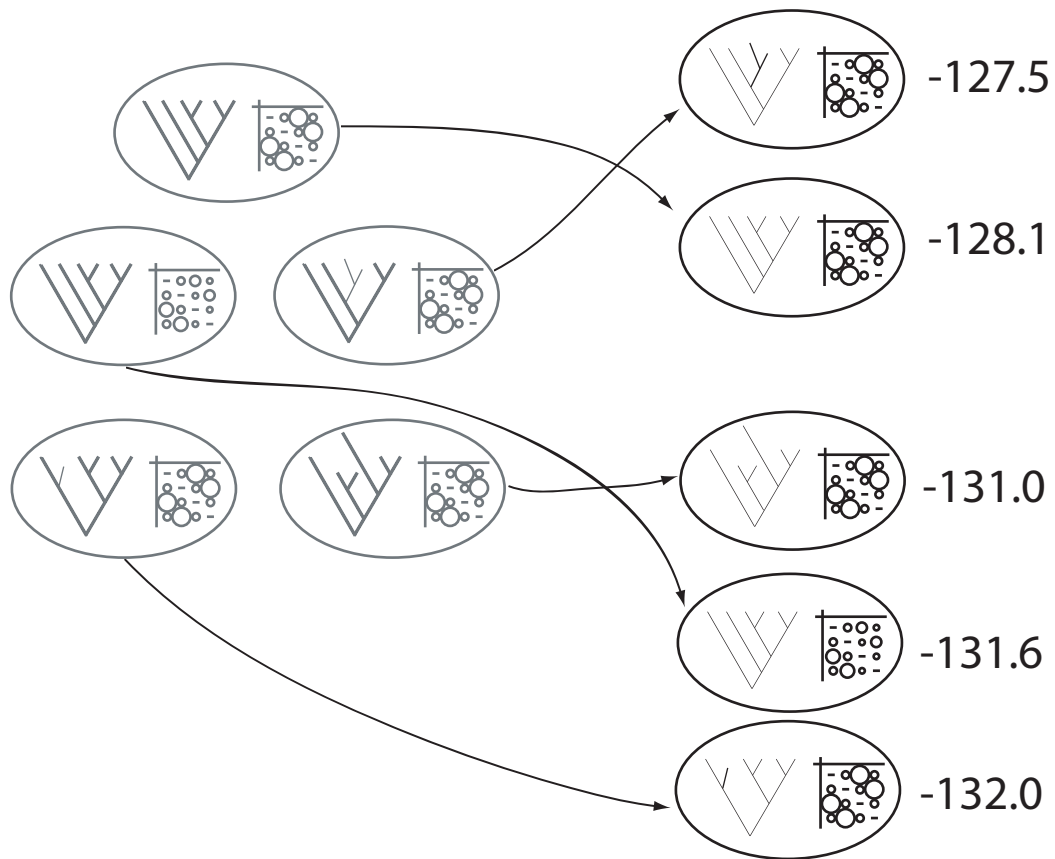
- Swapping need not include *all* neighbors (RAxML, reconlimit in PAUP*)
- “lazy” scoring of swaps (RAxML)
- Ignoring (at some stage) interactions between different branch swaps (PHYML)
- Stochastic searches
 - Genetic algorithms (GAML, MetaPIGA, GARLI)
 - Simulated annealing
- Divide and conquer methods (the sectorial searching of Goloboff, 1999; Rec-I-DCM3 Roshan 2004)
- Data perturbation methods (e.g. Kevin Nixon’s “ratchet”)

Population with variation

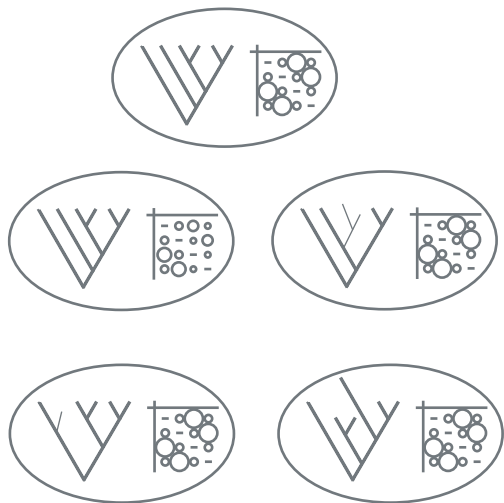


Population with variation

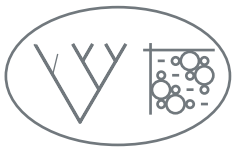
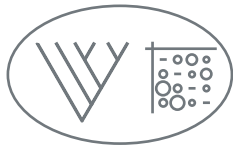
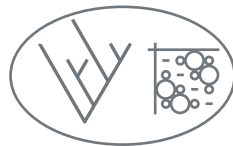
InL calculated



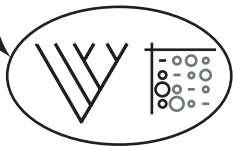
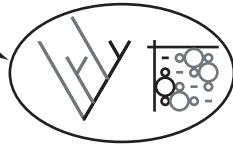
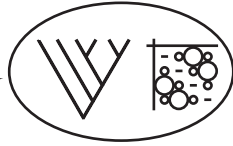
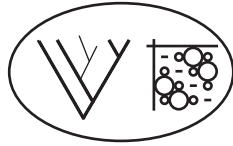
Population with variation



InL calculated



Fitness calculated



0.623

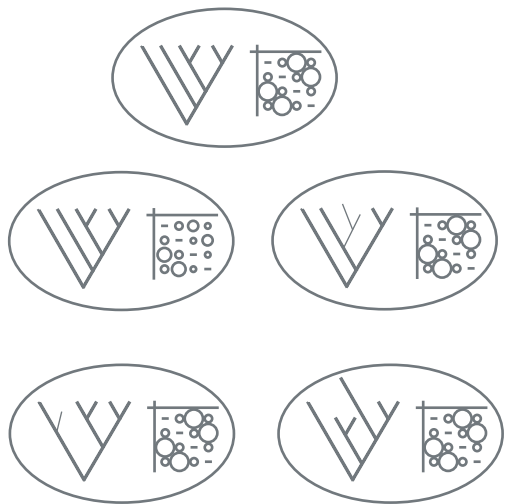
0.341

0.019

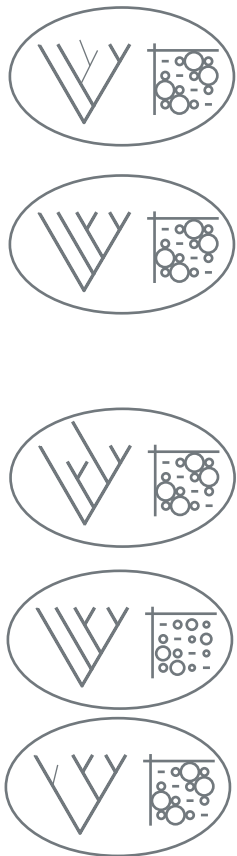
0.010

0.007

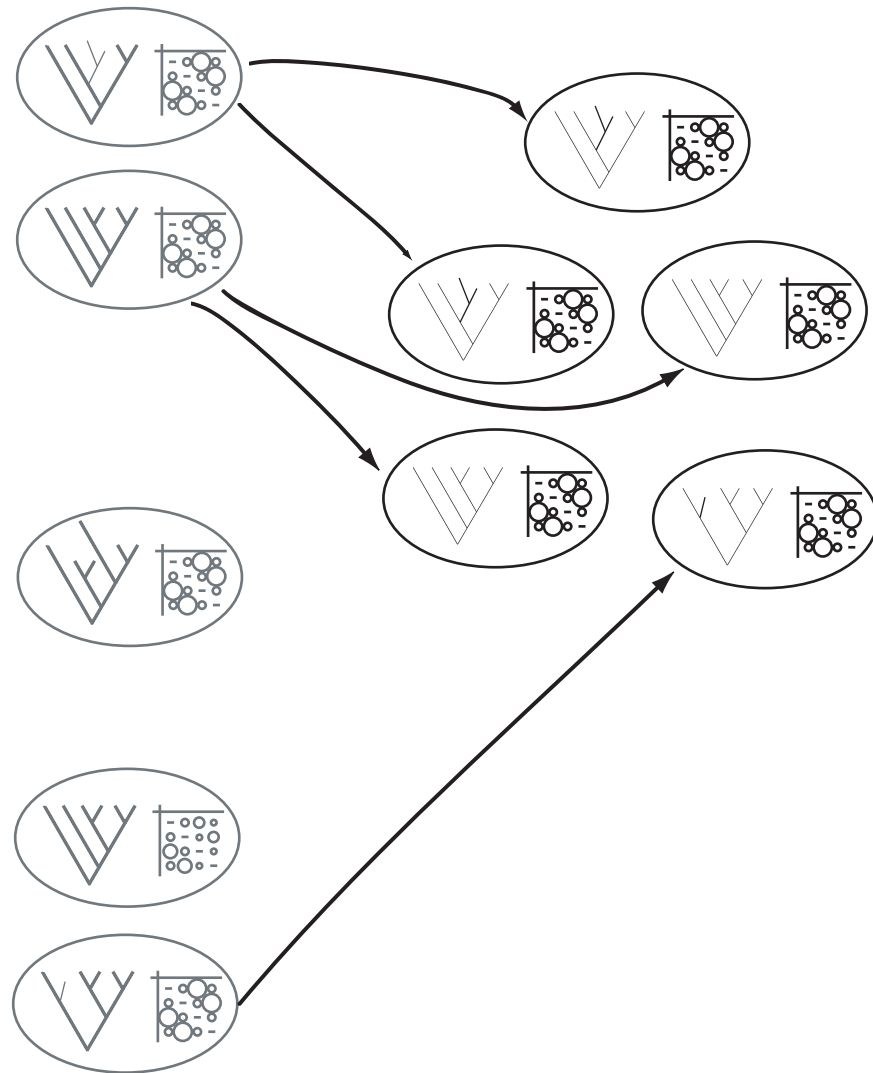
Population with variation



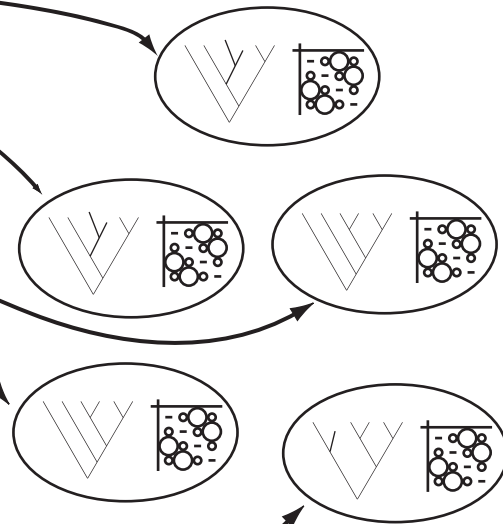
InL calculated



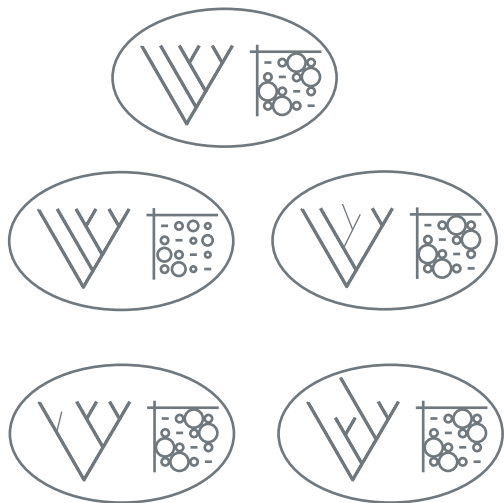
Fitness calculated



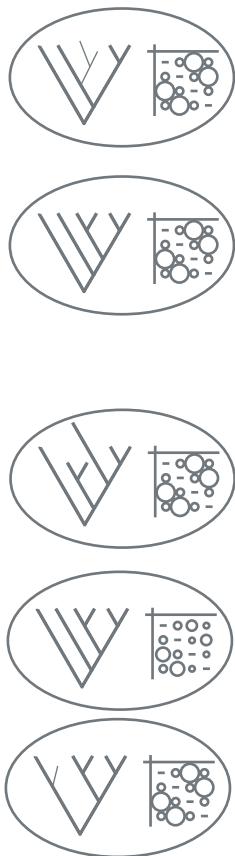
Selection



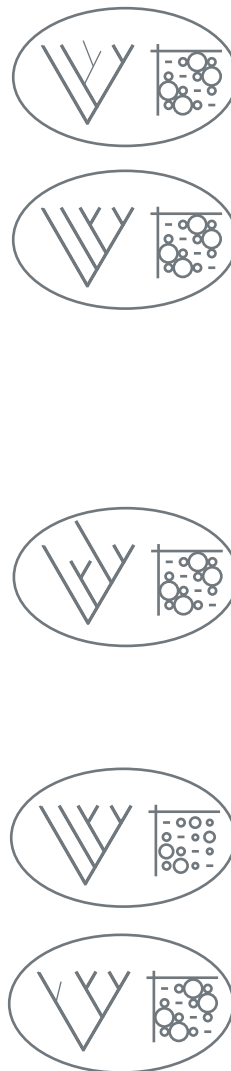
Population with variation



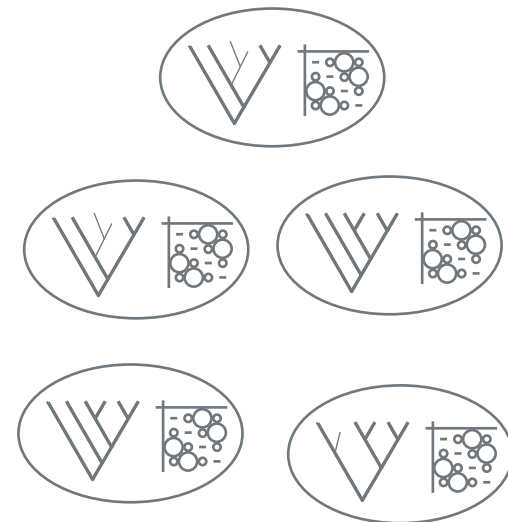
InL calculated



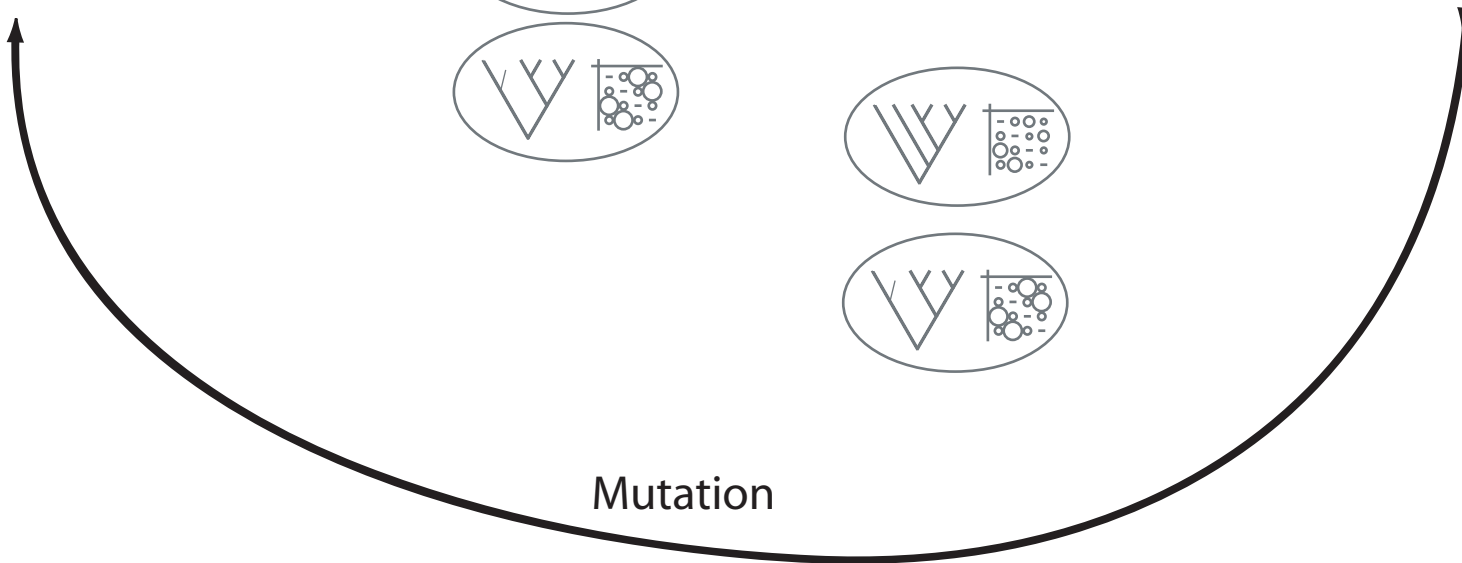
Fitness calculated



Selection



Mutation



Divide-and-Conquer Methods

The basic outline of a phylogenetic Divide-and-Conquer approach is:

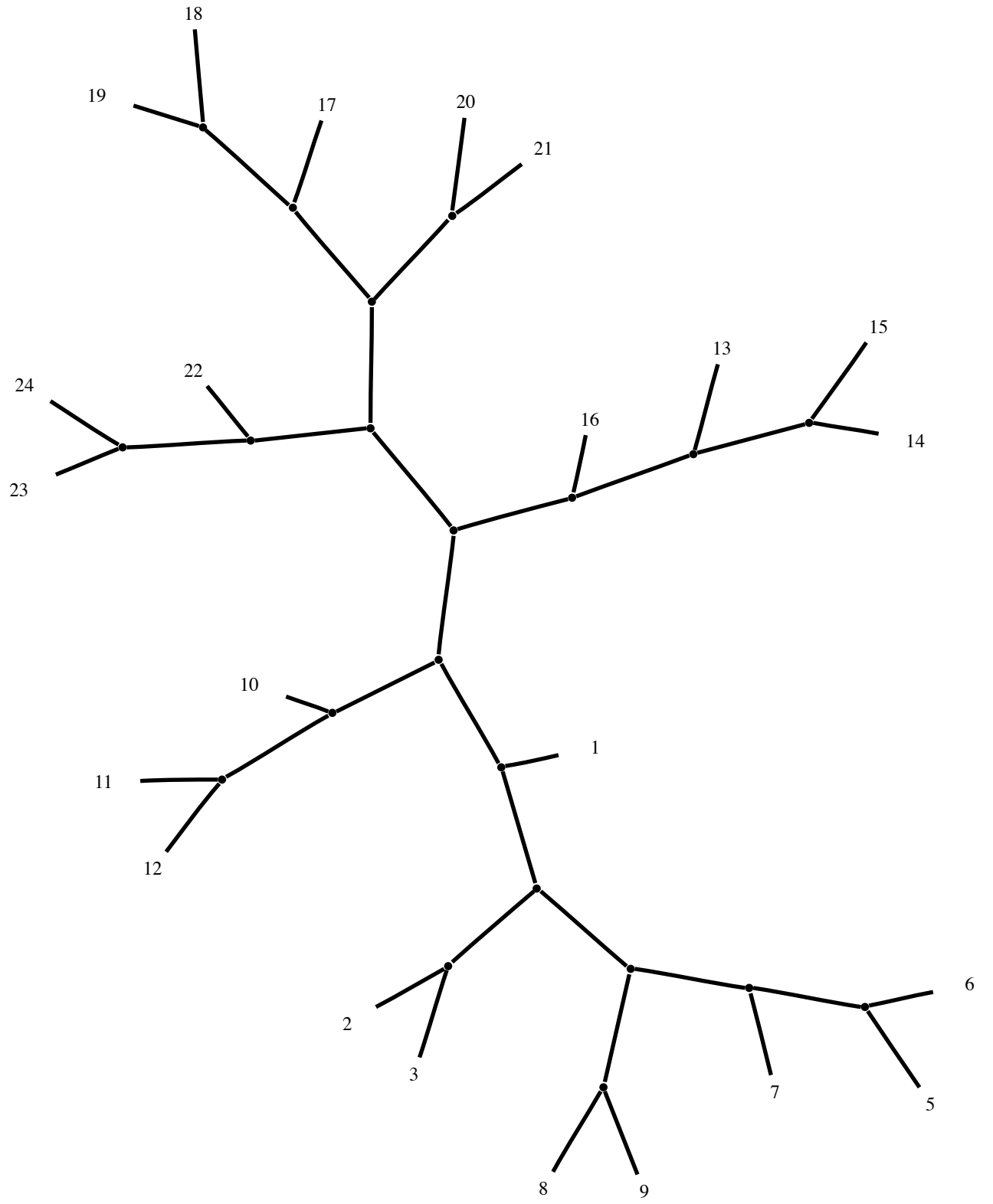
1. **Decompose** a starting tree into subsets of the taxa.
2. **Improve** the tree for each of the subsets of taxa.
3. **Merge** the resulting trees into a tree for the full set of taxa.
4. **Refine** the full tree (it will often have polytomies).
5. **Improve** the full tree using a simple (and fast) heuristic.

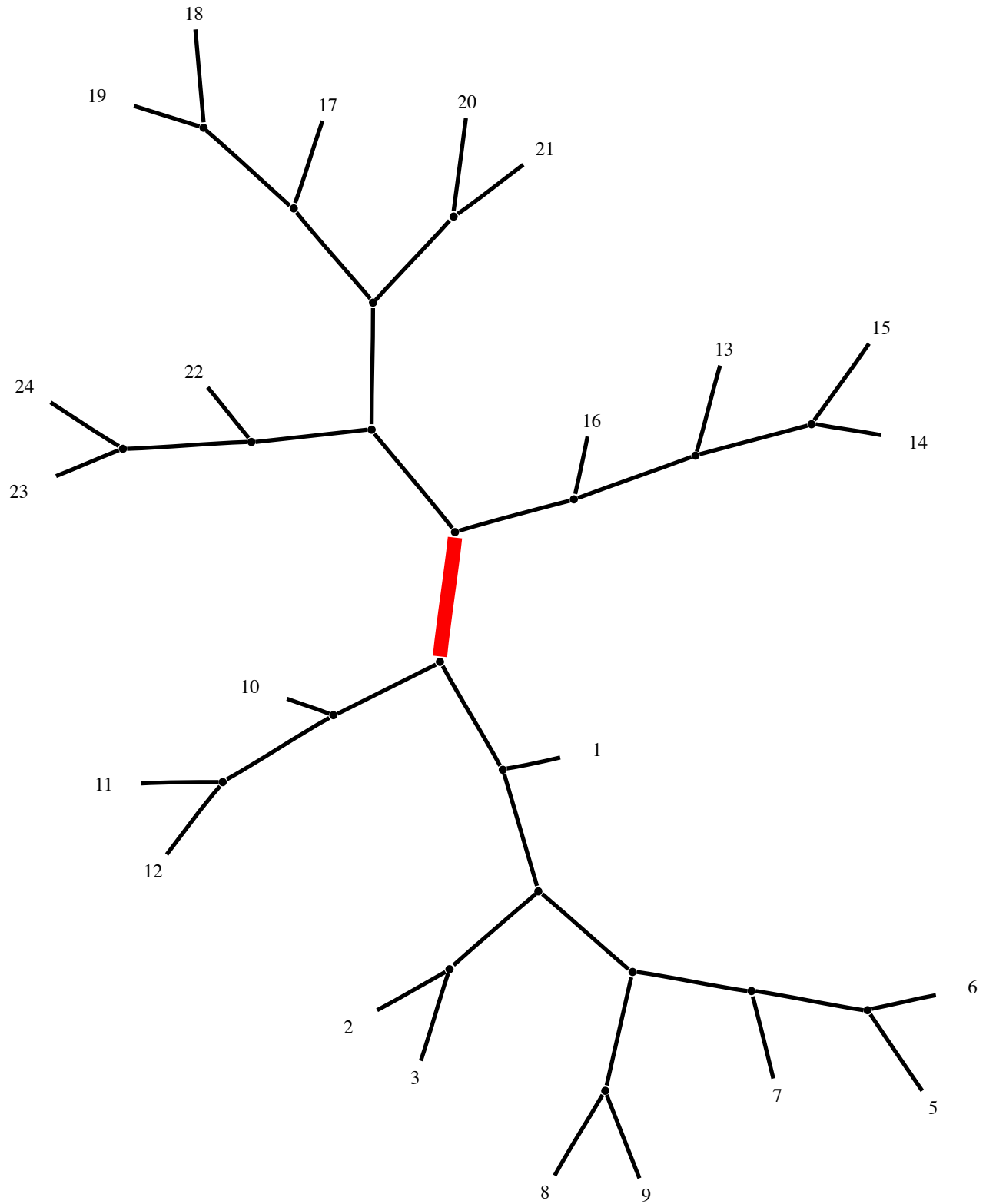
Examples include Rec-I-DCM3 by Roshan *et al.*(2004). See Goloboff and Pol (*Systematic Biology*, 2007) for a contrasting viewpoint about the relative efficiency of Rec-I-DCM3 compared to heuristics implemented in TNT.

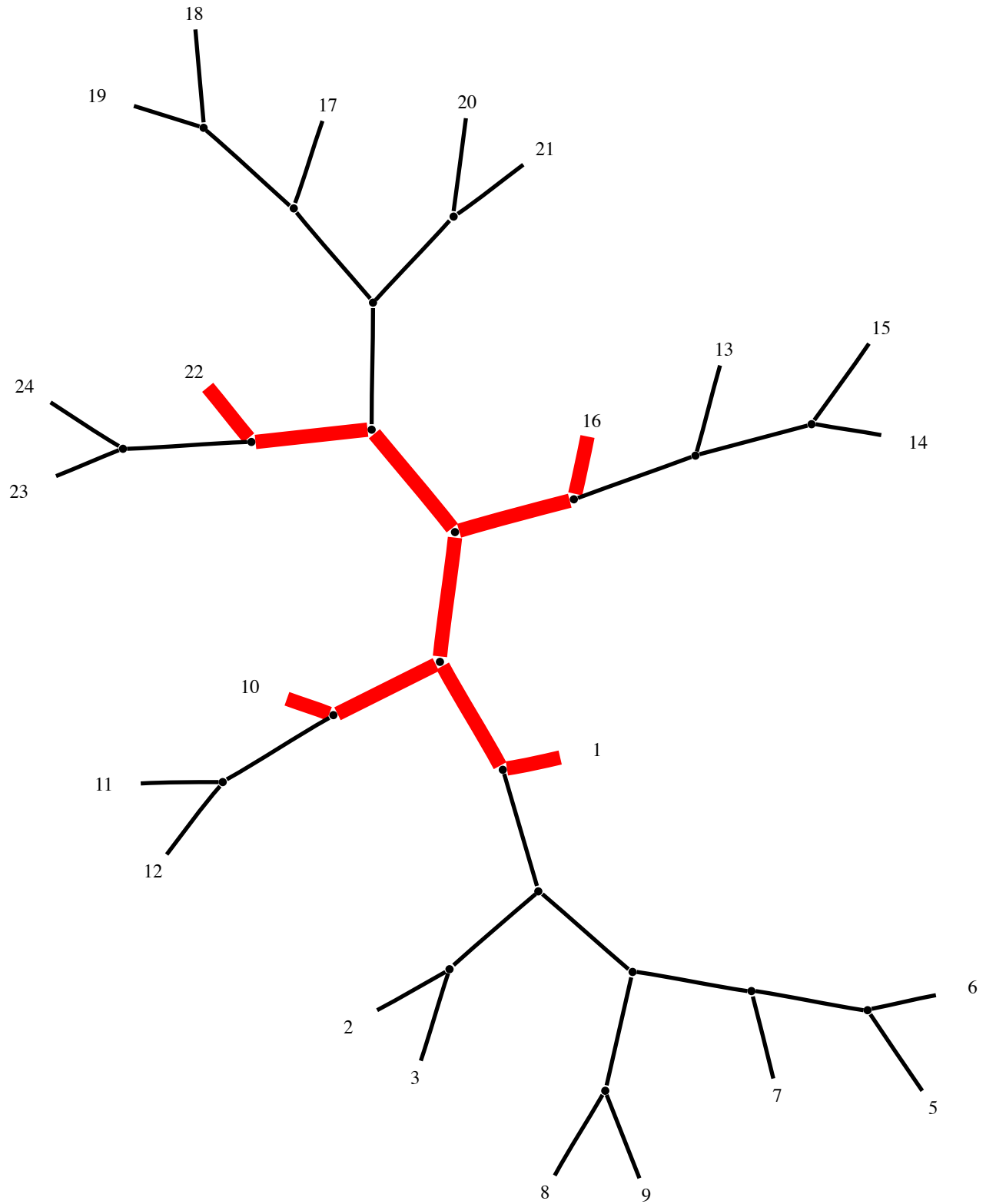
Step 1: Leaf set decomposition

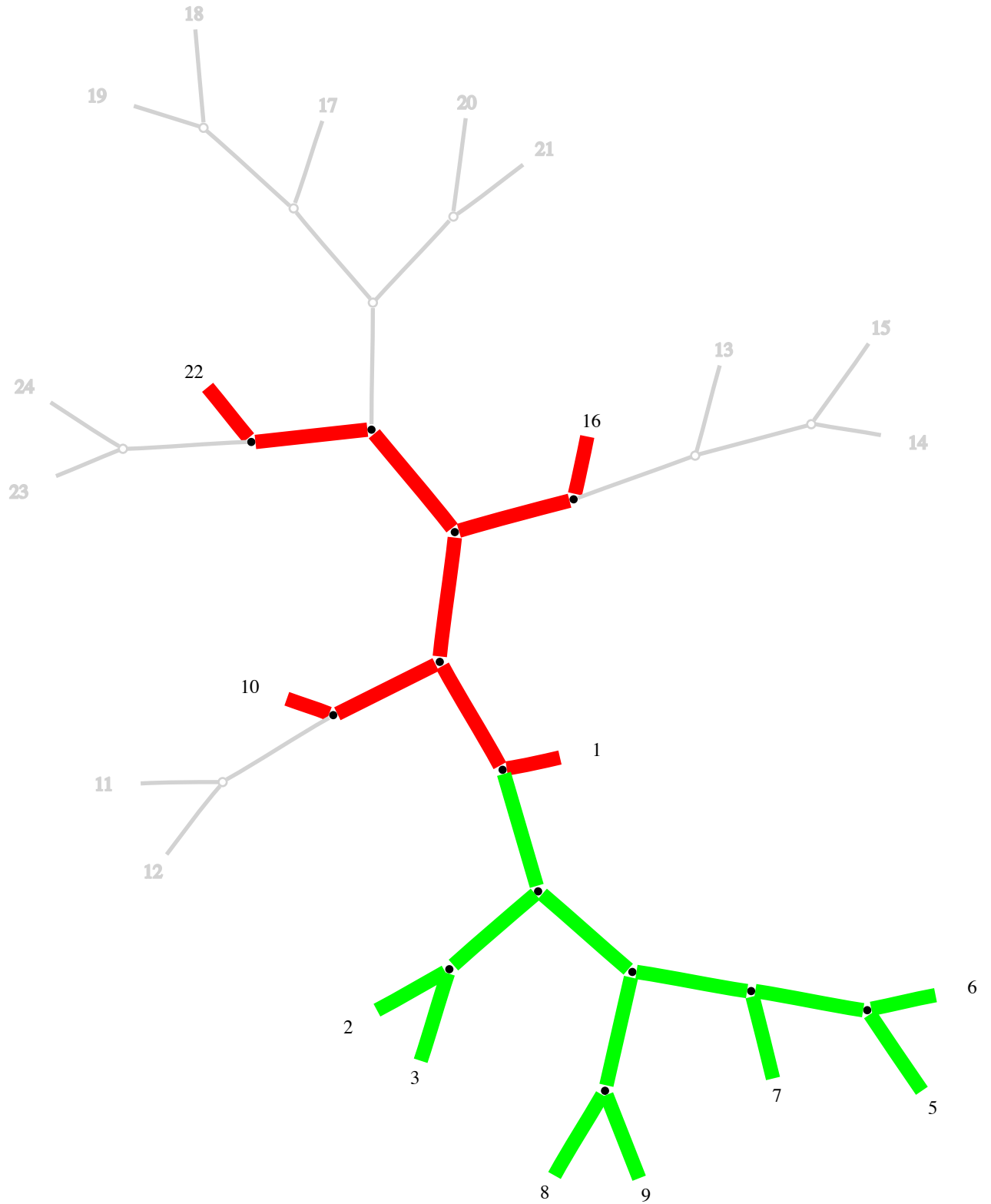
In Rec-I-DCM3 Roshan *et al.* (2004):

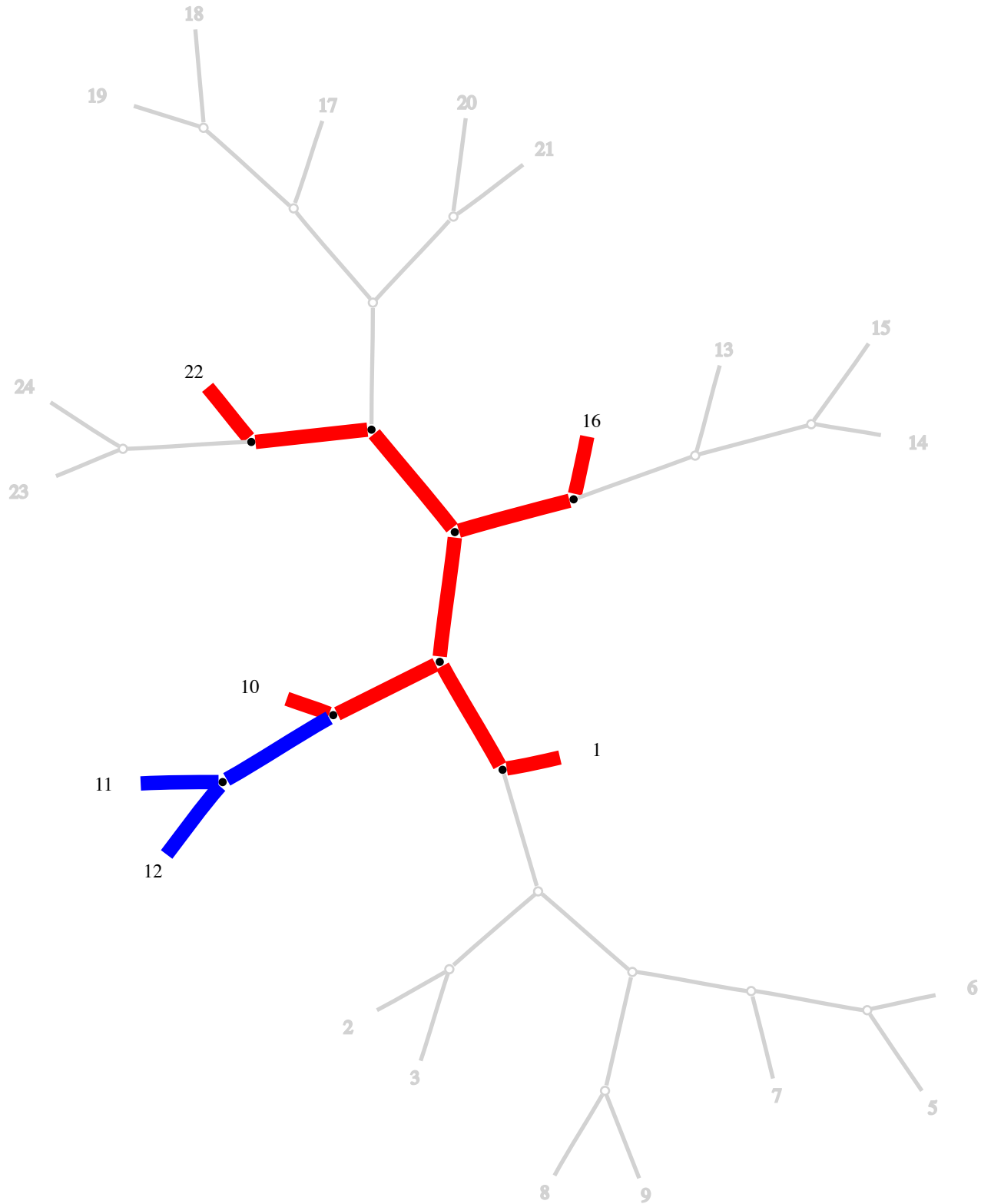
- A tree is divided (“decomposed”) into 4 trees around a central edge. The edge is chosen such that it comes as close as possible to dividing the taxa into 2 equally-sized groups.
- The short quartet (taxa closest to this edge in each of the 4 directions) is selected.
- 4 sub-problems are produced. Each contains 1 subtree connected to the central edge and all leaves that are a part of the short quartet.

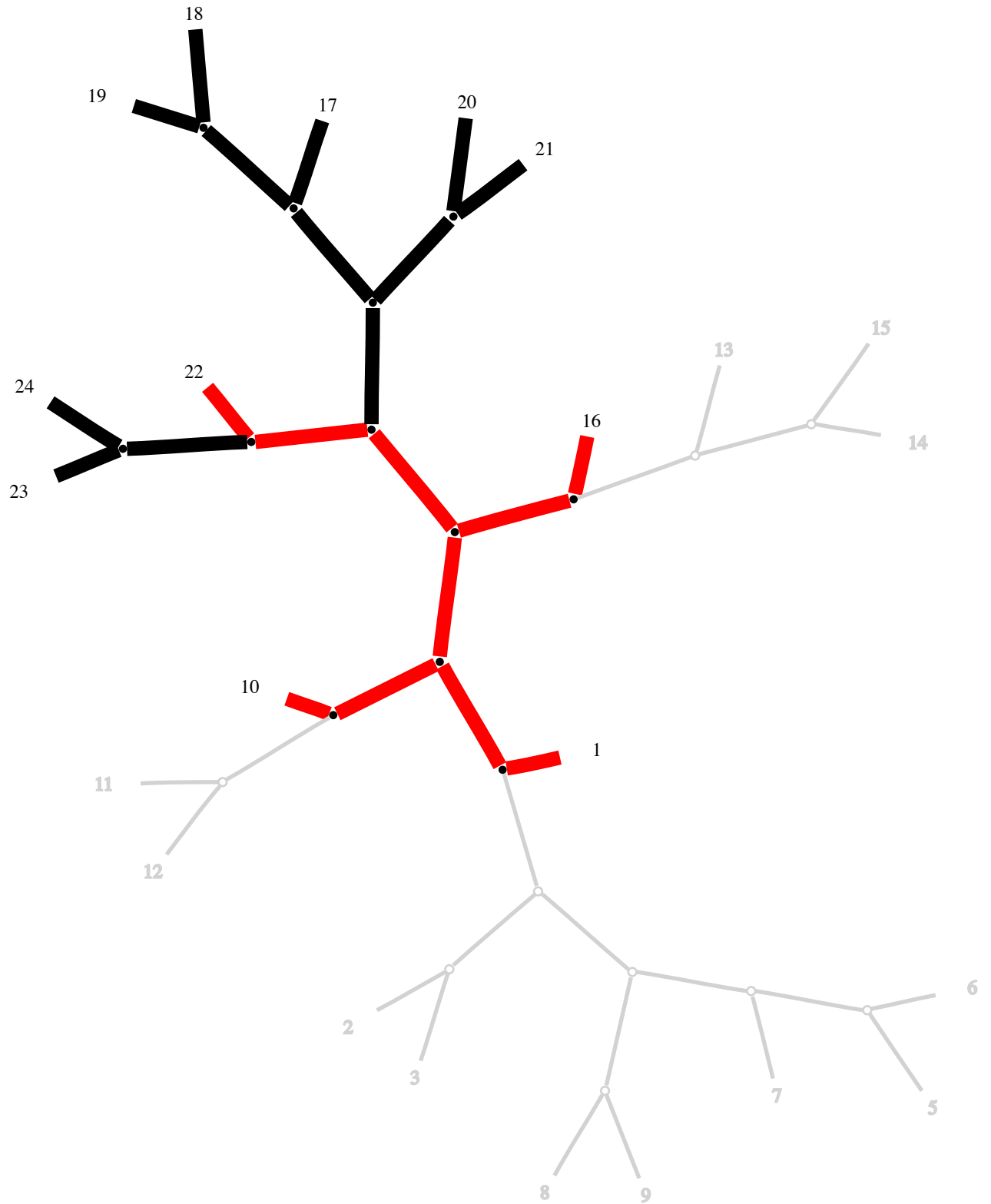


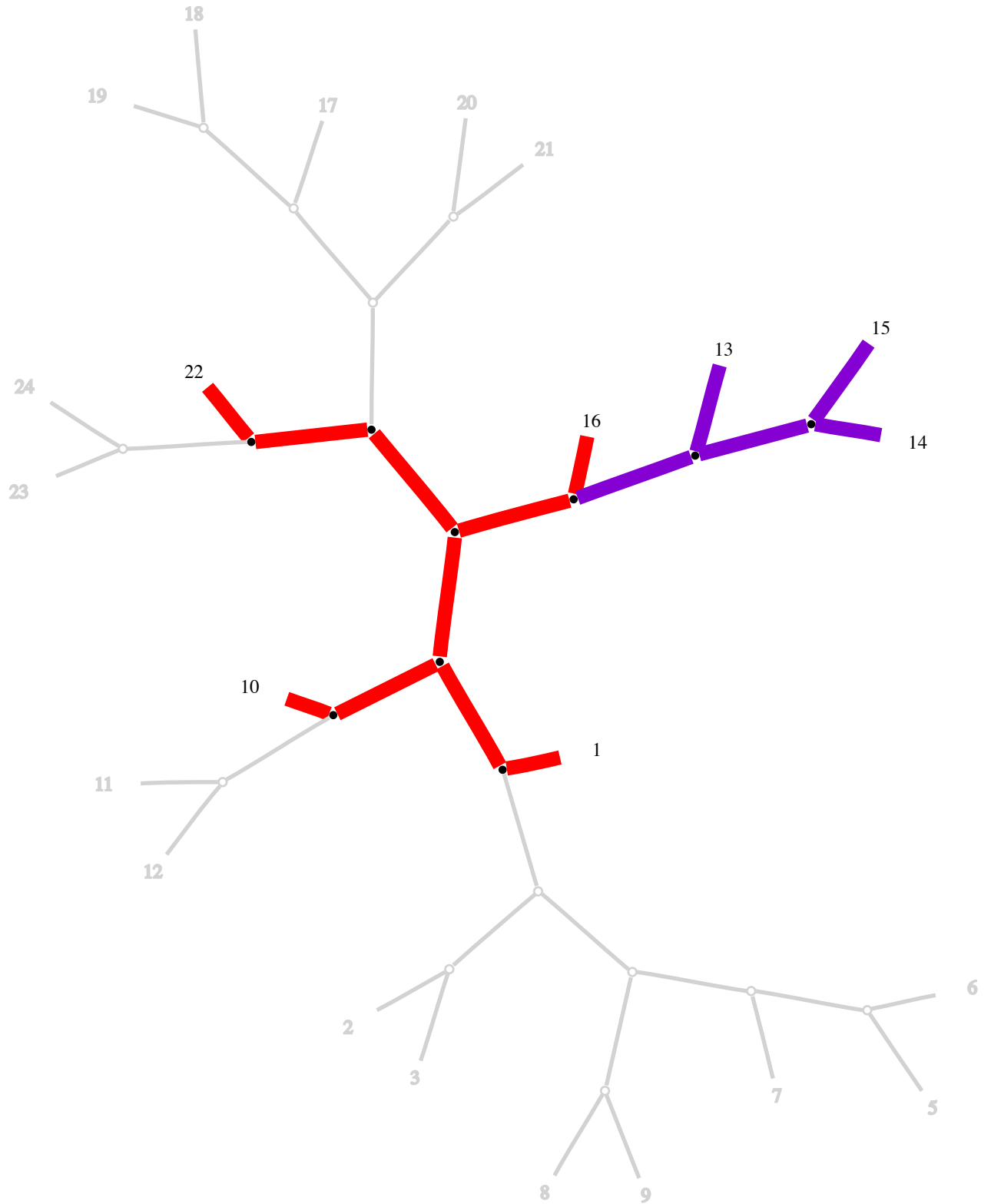












Step 2: Tree improvement

Simply a tree search on a smaller tree

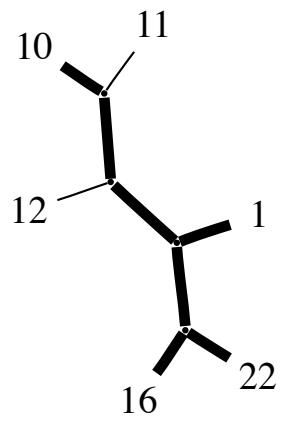
DCM is a “meta-method” that can be used with almost any type of large-scale tree inference.

Step 3: Tree Merge (Supertree analysis)

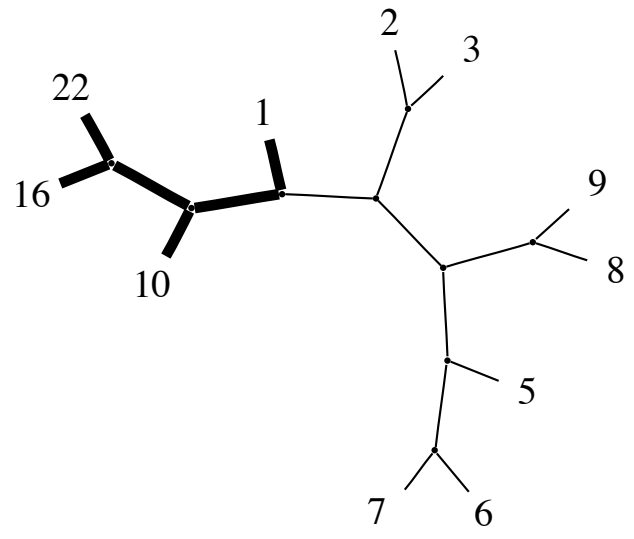
The step of “glueing” the trees for subproblems together is a supertree analysis.

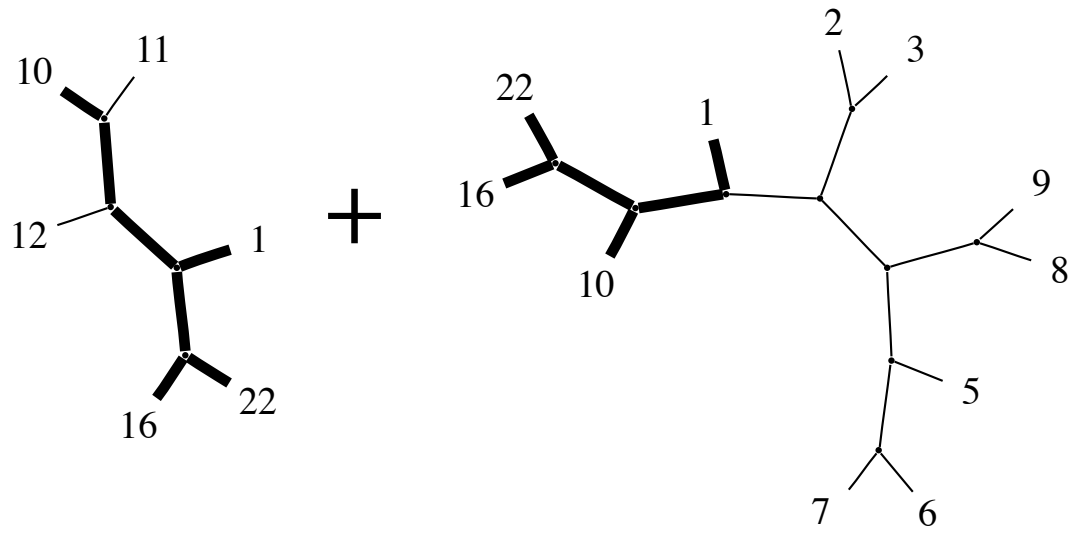
If there is no conflict between the input trees, the problem is trivial.

Roshan et recommend using a Strict Consensus Merger - collapse the minimal number of edges required to make 2 trees display the same tree (for the leaves that they have in common).



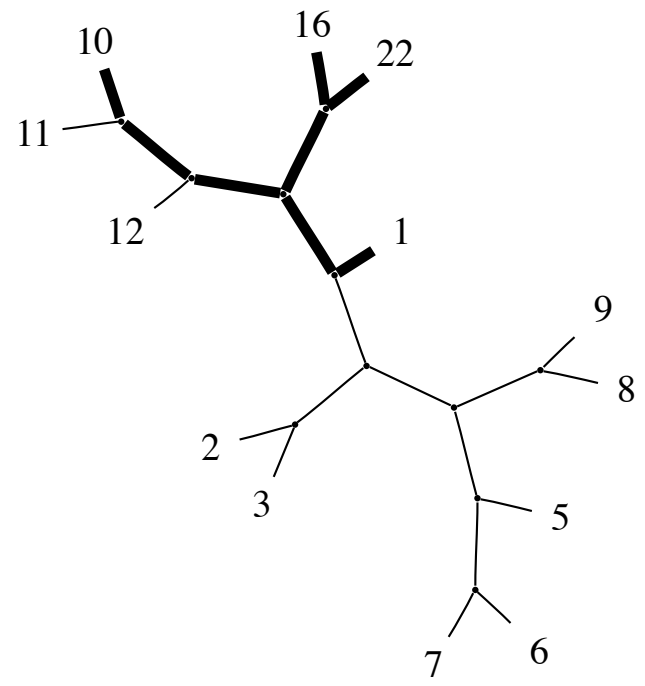
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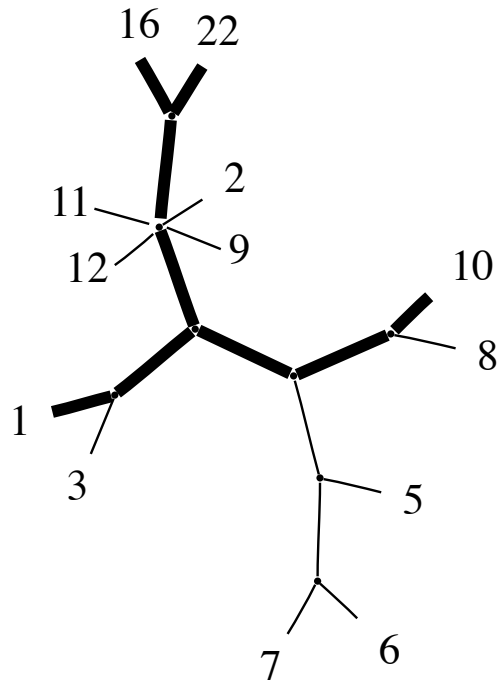
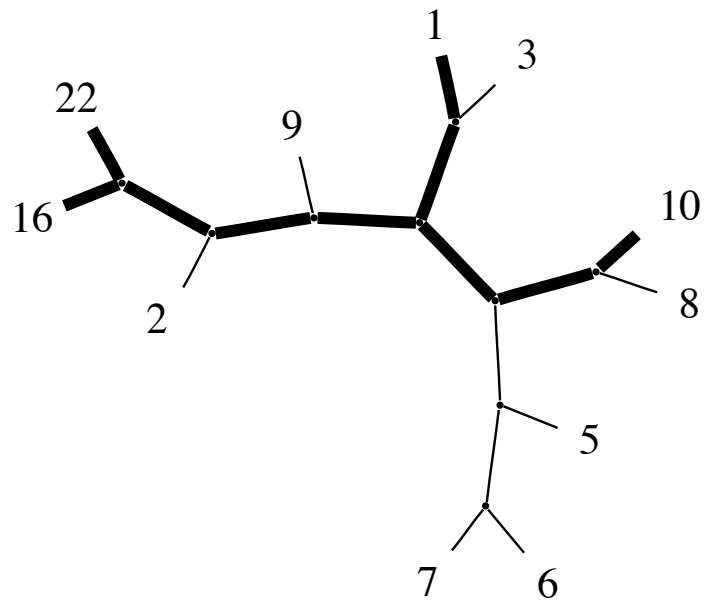
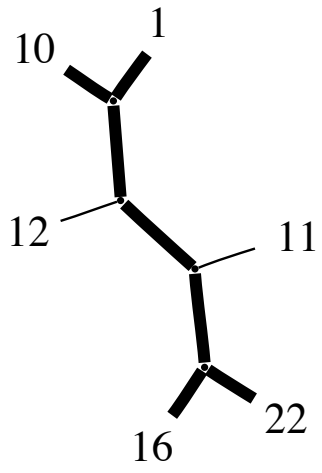




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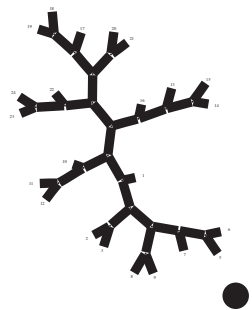


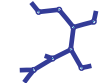
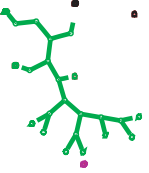
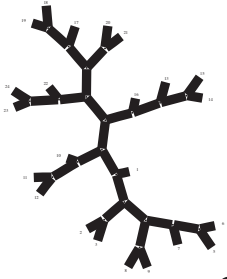
Step 4: Tree Refine

Optional step - some tree searching methods require binary trees

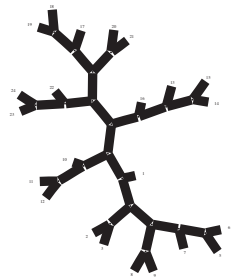
Step 5: Tree Improve

Another “base method” tree search (but with a large set of taxa, so the search often has to be less thorough)





Decompose

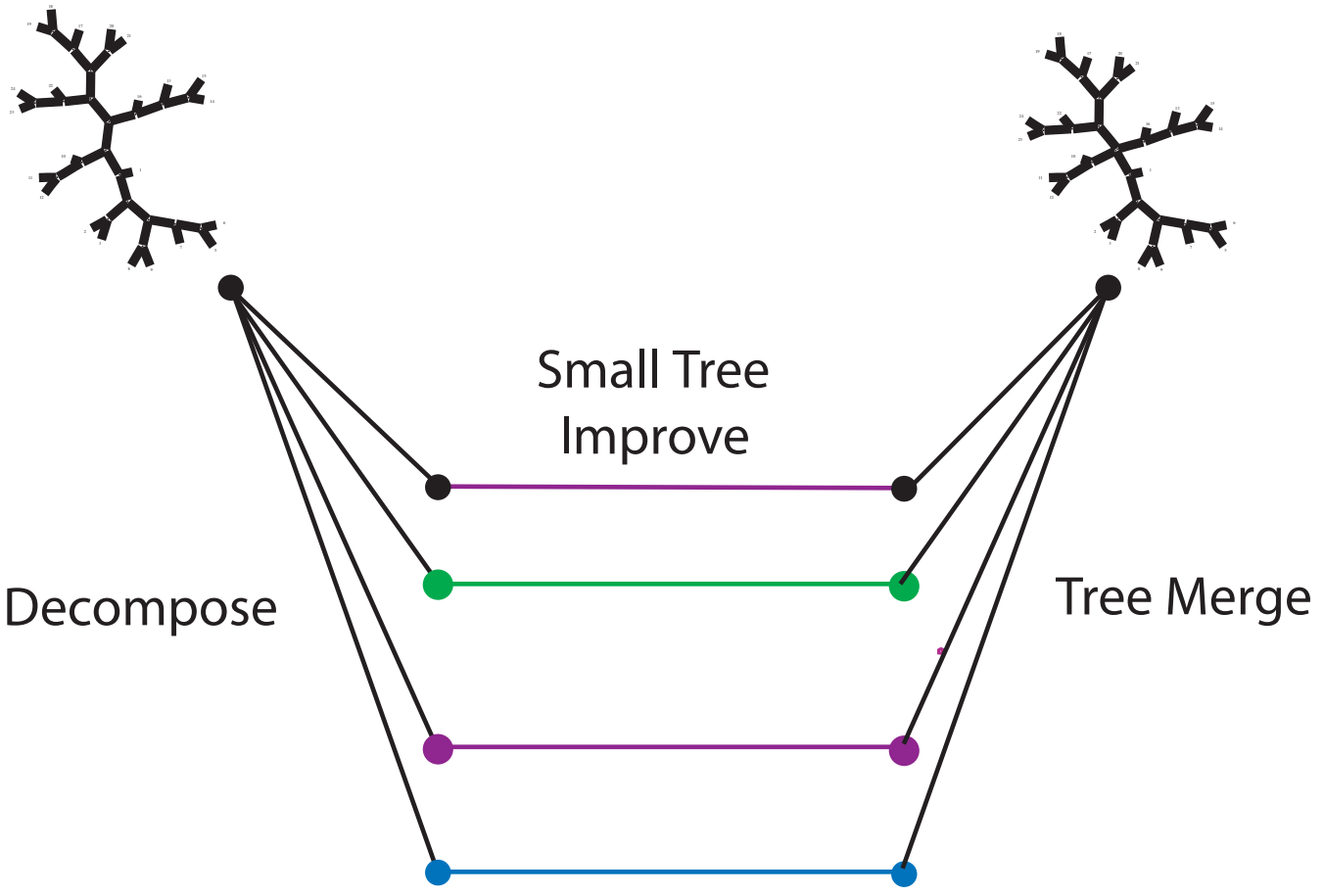


Decompose



Small Tree
Improve

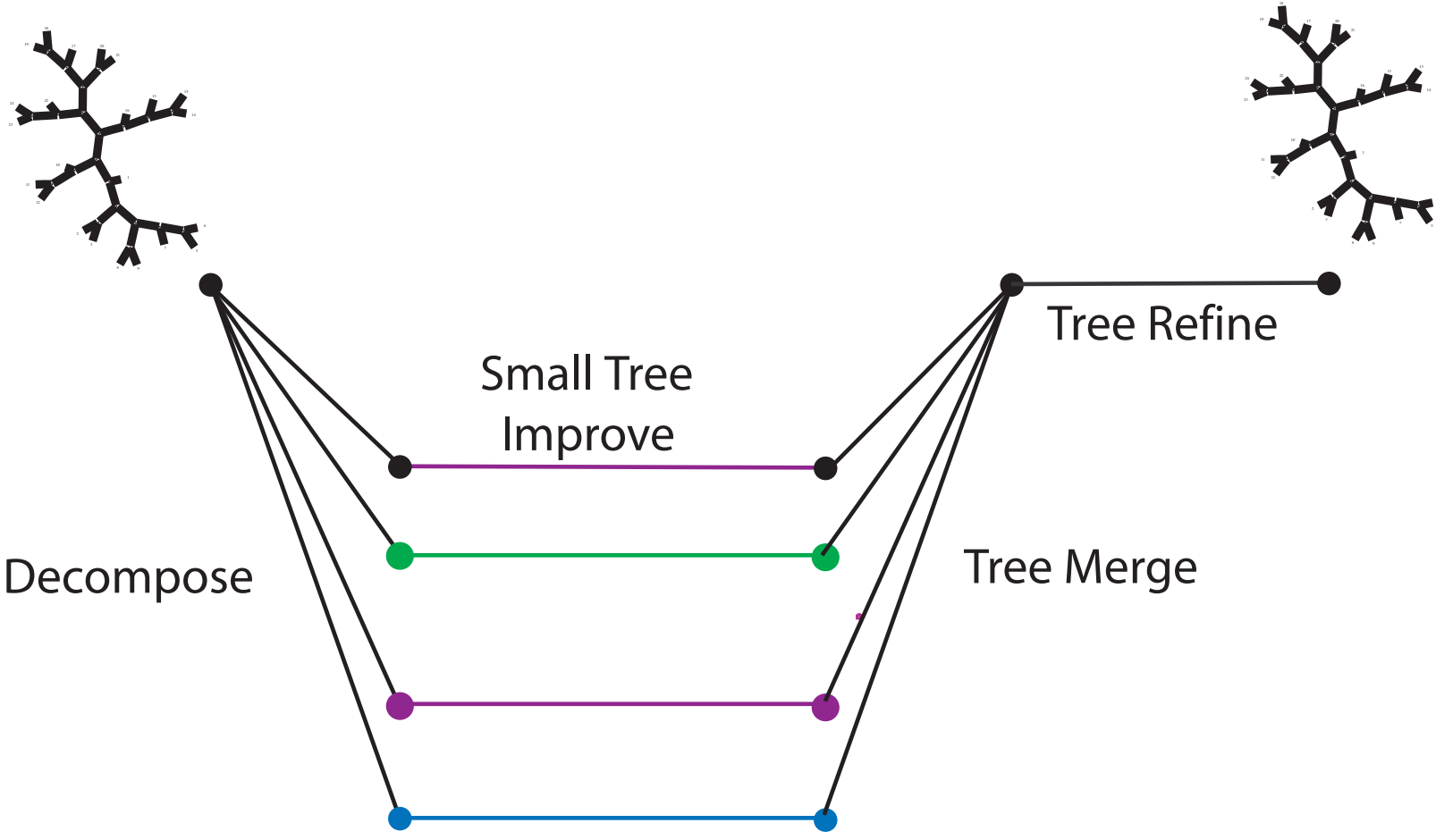


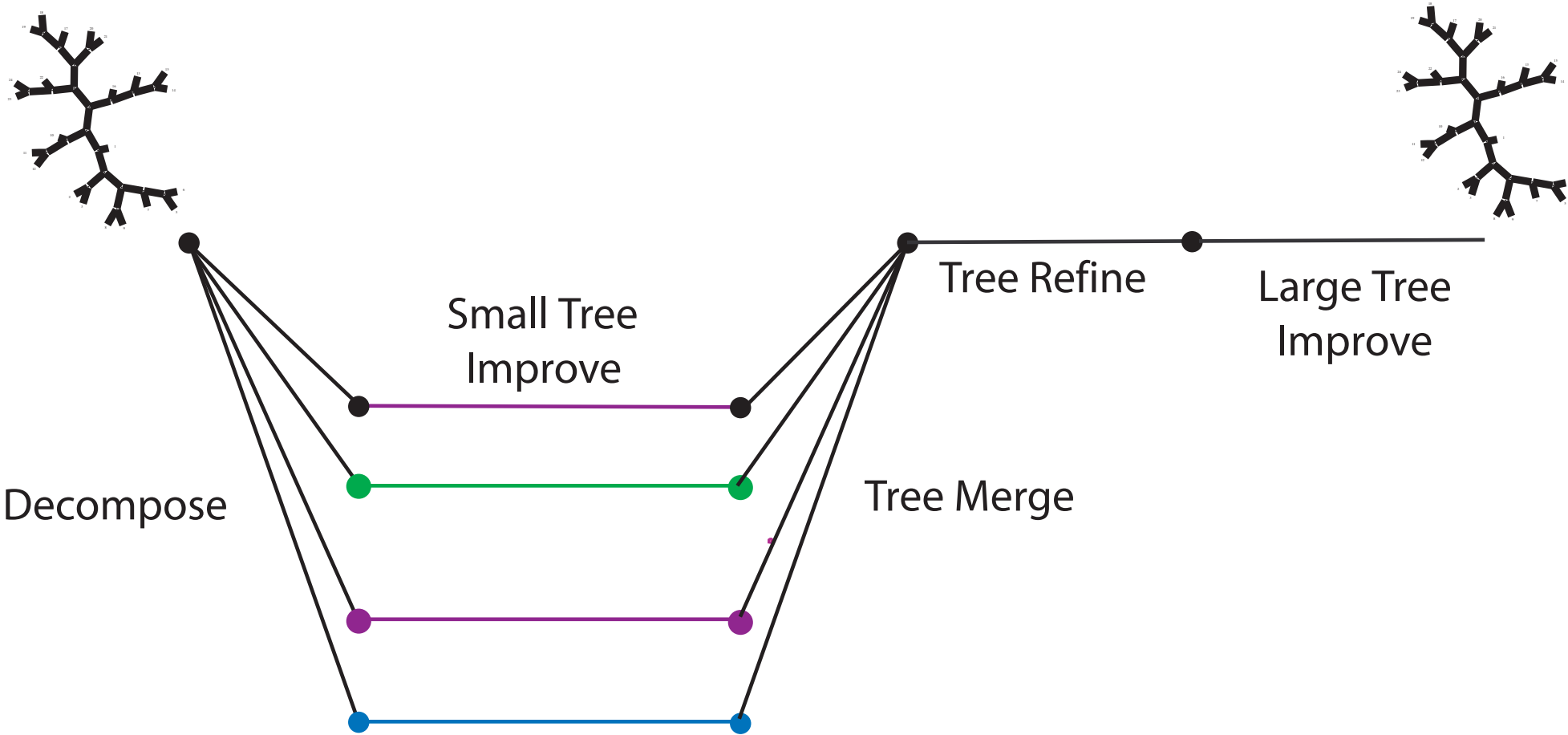


Small Tree
Improve

Decompose

Tree Merge





Small Tree
Improve

Decompose

Tree Merge

Tree Refine

Large Tree
Improve

Recursion

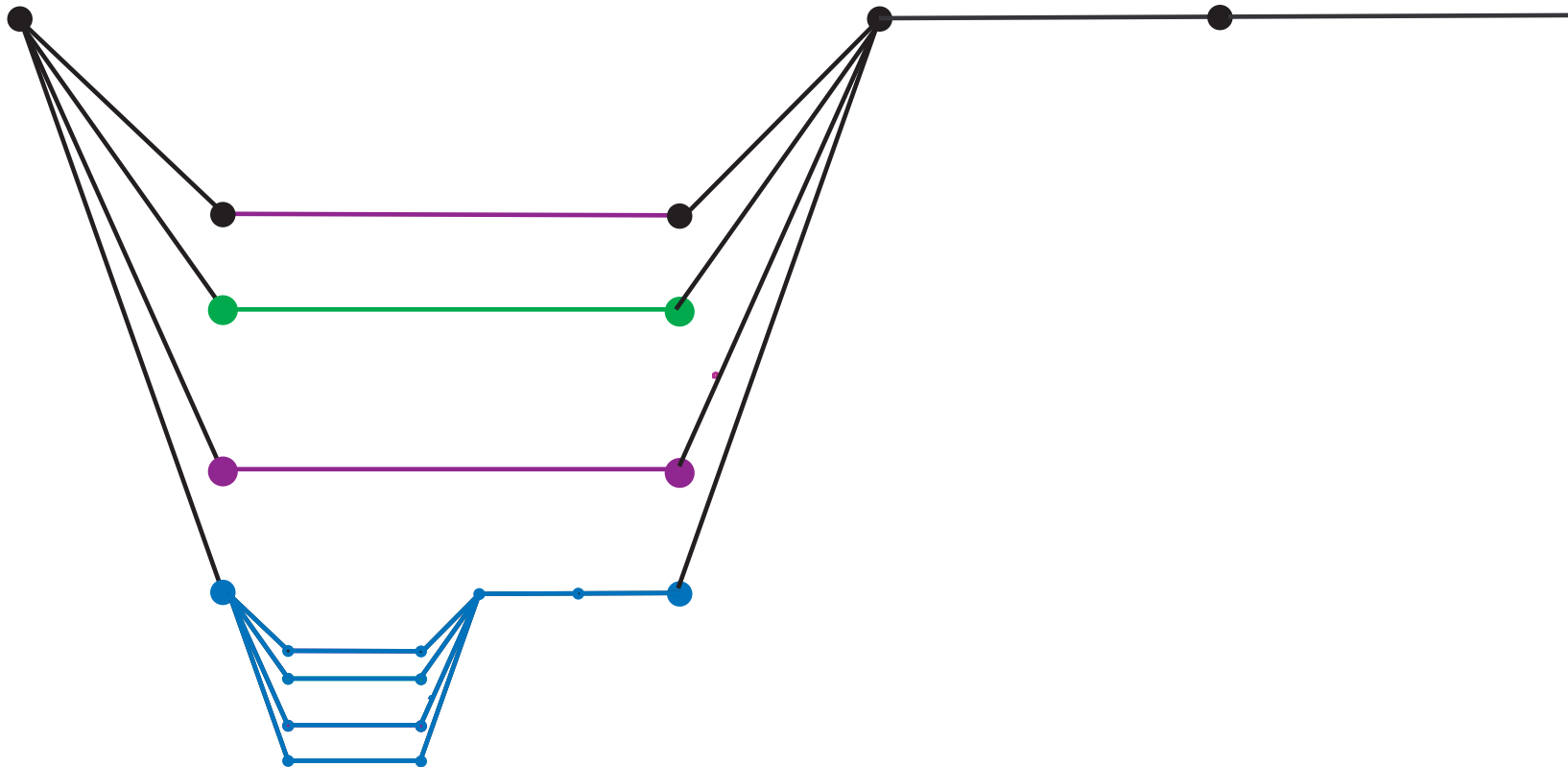
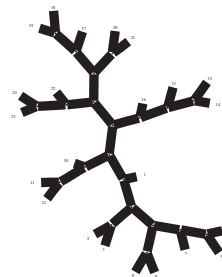
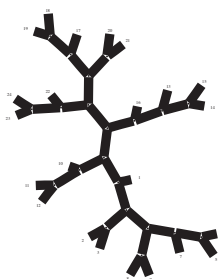
A *recursive* algorithm is one that calls (invokes) itself.

A definition of the function to compute the factorial is the classic example:

```
def factorial(n):  
    if n == 1:  
        return 1  
    else:  
        return n * factorial(n - 1)
```

Recursion is often used when it is easy to perform a few tasks, but then you are faced with the same problem you originally faced, but on a smaller scale.

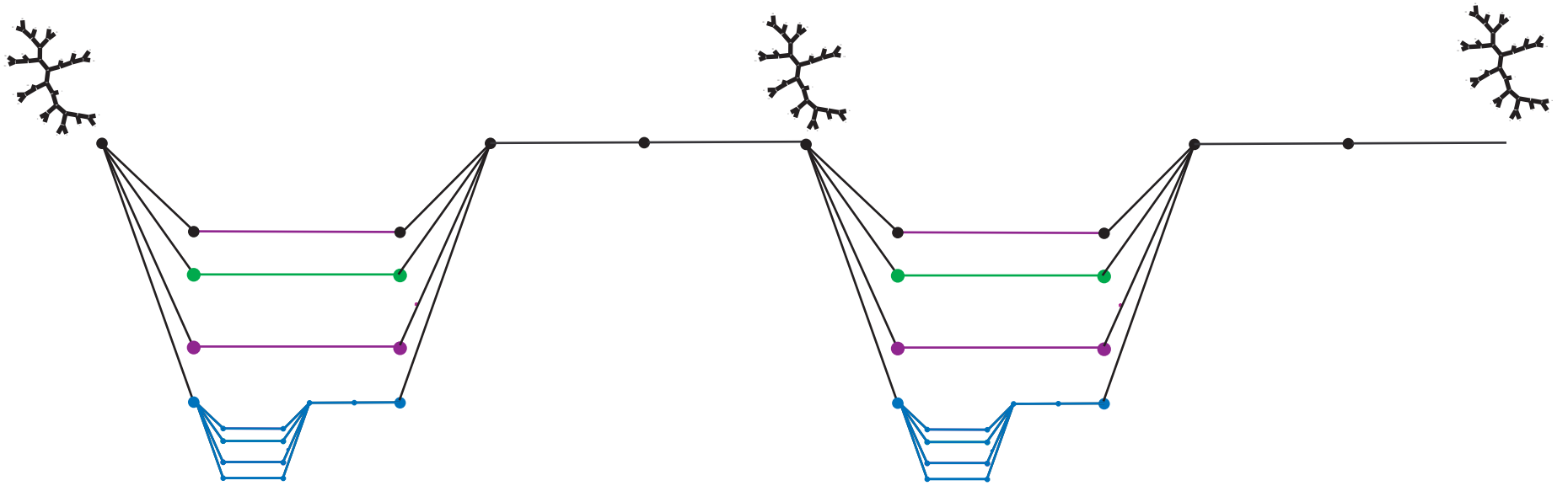
Recursive DCM3 arises from the recognition that, when we break our full set of taxa into subsets some of them may *still* be too large for thorough searching. We can use another level of DCM to break them down into smaller problems.



Iteration

Because the decompositions are sensitive to the starting tree, we may do a better job decomposing the tree into closely related subtrees if we have a better estimate of the tree.

So we can simply repeat the whole recursive DCM process



References

Maddison, D. (1991). The discovery and importance of multiple islands of most-parsimonious trees. *Systematic Zoology*, 40(3):315–328.